The X-ray transform on Anosov manifolds A survey of recent results

Thibault Lefeuvre

Joint works with Sébastien Gouëzel, Colin Guillarmou, Gerhard Knieper

Institut de Mathématique d'Orsay

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- (*M*, *g*) smooth closed connected *n*-dimensional Riemannian manifold,
- $X \in C^{\infty}(\mathcal{M}, T\mathcal{M})$ smooth vector field generating a transitive Anosov flow $(\varphi_t)_{t \in \mathbb{R}}$, i.e. such that there exists a continuous flow-invariant splitting

$$T\mathcal{M}=E_s\oplus E_u\oplus \mathbb{R}X,$$

with:

$$\begin{split} \|\mathrm{d}\varphi_t(v)\| &\leq C e^{-\lambda t} \|v\|, \ \forall v \in E_s, \forall t \geq 0, \\ \|\mathrm{d}\varphi_t(v)\| &\leq C e^{-\lambda |t|} \|v\|, \ \forall v \in E_u, \forall t \leq 0, \end{split}$$

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Setting of the problem Livsic theorems

• \mathcal{G} set of periodic orbits.

Definition (X-ray transform)

$$I: C^{0}(\mathcal{M}) \to \ell^{\infty}(\mathcal{G}), \qquad If: \mathcal{G} \ni \gamma \mapsto \langle \delta_{\gamma}, f \rangle := \frac{1}{\ell(\gamma)} \int_{0}^{\ell(\gamma)} f(\varphi_{t}z) \mathrm{d}t,$$

where $z \in \gamma$, $\ell(\gamma)$ is the period of γ .

- Definition can be restricted to other regularities: C^{α} (Hölder), H^{s} (Sobolev) for $s > \frac{n}{2}$, ...
- **Question:** can we describe the kernel of *I* on functions with prescribed regularity?
- I(Xu) = 0, for any $u \in C^{\infty}(\mathcal{M})$; Xu is called a coboundary.

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Theorem (Livsic '72)

Let $\alpha \in (0,1)$. Given $f \in C^{\alpha}(\mathcal{M})$ such that If = 0, there exists $u \in C^{\alpha}(\mathcal{M})$ such that f = Xu. Moreover, u is unique up to an additive constant.

Classical Livsic theorem was also proved:

- in smooth regularity i.e. f, u ∈ C[∞](M) (de la Llave-Marco-Moriyon '86),
- in Sobolev regularity i.e. $f, u \in H^{s}(\mathcal{M})$ (Guillarmou '17).

- What if *If* ≥ 0 instead of *If* = 0? (Positive version of Livsic theorem)
- What if $If \simeq \varepsilon$ (i.e. $||If||_{\ell^{\infty}} := \sup_{\gamma \in \mathcal{G}} |If(\gamma)| \le \varepsilon$)? (Approximate Livsic theorem)
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Theorem (Lopes-Thieullen '04, Positive Livsic theorem)

Let $\alpha \in (0, 1)$. There exists $\beta \in (0, \alpha)$, C > 0 such that the following holds. Let $f \in C^{\alpha}(\mathcal{M})$ such that $If \geq 0$. Then, there exists $u, h \in C^{\beta}(\mathcal{M})$ such that $Xu \in C^{\beta}(\mathcal{M})$, $h \geq 0$ and f = Xu + h. (In particular, $f \geq Xu$.) Moreover, $\|h\|_{C^{\beta}} + \|Xu\|_{C^{\beta}} \leq C\|f\|_{C^{\alpha}}$.

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Theorem (Gouëzel-L. '19, Approximate Livsic theorem)

Let $\alpha \in (0, 1)$. There exists $\beta \in (0, \alpha), \nu > 0$ such that the following holds. For any $\varepsilon > 0$ small enough, given $f \in C^{\alpha}(\mathcal{M})$ such that $\|f\|_{C^{\alpha}} \leq 1$ and $\|If\|_{\ell^{\infty}} \leq \varepsilon$, there exists $u, h \in C^{\beta}(\mathcal{M})$ such that $Xu \in C^{\beta}(\mathcal{M}), \|h\|_{C^{\beta}} \leq \varepsilon^{\nu}$ and f = Xu + h.

Theorem (**Gouëzel-L. '19**, Finite Livsic theorem)

Let $\alpha \in (0,1)$. There exists $\beta \in (0, \alpha), \mu > 0$ such that the following holds. For any L > 0 large enough, given $f \in C^{\alpha}(\mathcal{M})$ such that $\|f\|_{C^{\alpha}} \leq 1$ and $If(\gamma) = 0$ for all $\gamma \in \mathcal{G}$ such that $\ell(\gamma) \leq L$, there exists $u, h \in C^{\beta}(\mathcal{M})$ such that $Xu \in C^{\beta}(\mathcal{M}), \|h\|_{C^{\beta}} \leq L^{-\mu}$ and f = Xu + h. This implies that $\|If\|_{\ell^{\infty}} \leq L^{-\mu}$.

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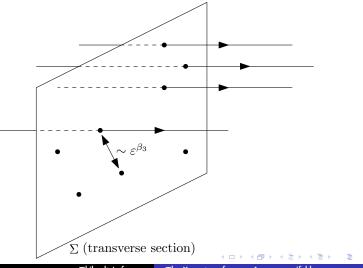
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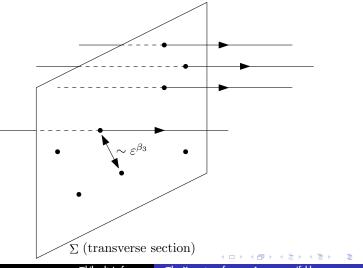
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- (M,g) smooth connected closed Riemannian manifold with Anosov geodesic flow (φ_t)_{t∈ℝ} on its unit tangent bundle M := SM. We call (M,g) an Anosov Riemannian manifold.
- C is the set of free homotopy classes; there exists a unique closed geodesic in each free homotopy class c ∈ C (Klingenberg '74). We identify G and C.
- C[∞](M, ⊗^m_S T^{*}M) is the vector-space of smooth symmetric m-tensors (m ∈ N).

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• Symmetric tensors on M can be seen as functions on the unit tangent bundle SM, polynomial in the spheric variable. Given $m \in \mathbb{N}, f \in C^0(M, \bigotimes_S^m T^*M)$, we define $\pi_m^* f \in C^0(SM)$ by $\pi_m^* f : (x, v) \mapsto f_x(v, ..., v)$.

Definition (Geodesic X-ray transform)

$$I_m: C^0(M, \otimes_S^m T^*M) \to \ell^\infty(\mathcal{C}),$$
$$I_m f = I\pi_m^* f: \mathcal{C} \ \ni c \mapsto \frac{1}{\ell(\gamma_c)} \int_0^{\ell(\gamma_c)} f_{\gamma_c(t)}(\dot{\gamma}_c(t), ..., \dot{\gamma}_c(t)) \mathrm{d}t,$$

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Stability estimates Idea of proof

• Tensor decomposition:

f=Dp+h,

with $D := \sigma \circ \nabla$ (∇ Levi-Civita connexion, σ symmetrization operator of tensors), $D^*h = 0$ where D^* is the formal adjoint of D. We call Dp the potential part and h the solenoidal part of f.

I_m(Dp) = 0, that is {potential tensors} ⊂ ker *I_m*. *I_m* is said to be s(olenoidal)-injective when this is an equality.

Conjecture

 I_m is s-injective whenever (M,g) is an Anosov Riemannian manifold.

Known results when (M, g) Anosov; I_m is s-injective for:

• any $m \in \mathbb{N}$ on surfaces (Paternain-Salo-Uhlmann '14, Guillarmou '17),

 any m ∈ N in any dimension, in nonpositive curvature (Croke-Sharafutdinov '98),

• m = 0, 1 in any dimension (**Dairbekov-Sharafutdinov-11**).

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 I_m is s-injective whenever (M, g) is an Anosov Riemannian manifold.

Known results when (M, g) Anosov; I_m is s-injective for:

- any $m \in \mathbb{N}$ on surfaces (Paternain-Salo-Uhlmann '14, Guillarmou '17),
- any $m \in \mathbb{N}$ in any dimension, in nonpositive curvature (Croke-Sharafutdinov '98),
- m = 0, 1 in any dimension (**Dairbekov-Sharafutdinov-11**).

• **Question:** Once we have s-injectivity, can we obtain a stability estimate of the form

 $\|f\|_{\mathcal{H}_{\mathbf{1}}} \leq C \|I_m f\|_{\mathcal{H}_{\mathbf{2}}}, \quad \forall f \text{ solenoidal},$

for some well-chosen spaces $\mathcal{H}_{1,2}$?

Theorem (Guillarmou-L. '18, Gouëzel-L. '19)

For all exponents n/2 < s < r, there exists $C, \nu > 0$ such that the following holds. For all solenoidal tensors f such that $||f||_{H^r} \le 1$, one has:

 $\|f\|_{H^s} \leq C \|I_m f\|_{\ell^{\infty}}^{\nu}$

Now, recall the Finite Livsic theorem:

Theorem (**Gouëzel-L. '19**, Finite Livsic theorem)

For any L > 0 large enough, given $f \in C^{\alpha}(\mathcal{M})$ such that $||f||_{C^{\alpha}} \leq 1$ and $lf(\gamma) = 0$ for all $\gamma \in \mathcal{G}$ such that $\ell(\gamma) \leq L$, there exists $u, h \in C^{\beta}(\mathcal{M})$ such that $Xu \in C^{\beta}(\mathcal{M}), ||h||_{C^{\beta}} \leq L^{-\mu}$ and f = Xu + h. This implies that $||If||_{\ell^{\infty}} \leq L^{-\mu}$.

• **Question:** Once we have s-injectivity, can we obtain a stability estimate of the form

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Combining the two previous theorems, we obtain the

Corollary (Gouëzel-L. '19)

For all exponents n/2 < s < r, there exists $\mu > 0$ such that the following holds. For any L > 0 large enough, given any solenoidal tensor f such that $||f||_{H^r} \le 1$ and $I_m f(c) = 0$ for all $c \in C$ such that $\ell(\gamma_c) \le L$, one has: $||f||_{H^s} \le L^{-\mu}$. (In particular, $L = +\infty$ is the Classical Livsic theorem.)

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- The X-ray transform *I* has bad analytic properties (in particular, it maps to functions on a discrete set).
- Idea (Guillarmou '17): Mimick the case of a simple manifold with boundary (smwb). On a smwb, we can write the normal operator

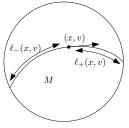
$$l^*l = \int_{-\infty}^{+\infty} e^{tX} \mathrm{d}t$$



$$I_m^*I_m = \pi_{m*}I^*I\pi_m^*$$

is a ΨDO of order -1, elliptic on solenoidal tensors.

If R_±(λ) := (X ± λ)⁻¹ denotes the resolvent of the generator of the geodesic flow, then I^{*}I = R₊(0) − R_−(0).



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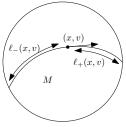
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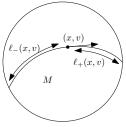
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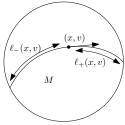
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- R_±(λ) := (X ± λ)⁻¹ (initially defined for ℜ(λ) > 0) can be meromorphically extended to the whole complex plane (Faure-Sjöstrand '11, Dyatlov-Zworski '16).
- R_±(λ) have a pole of order 1 at 0; we denote by R₀[±] the holomorphic part of R_±(λ) at λ = 0. We set:

$$\Pi := R_0^+ - R_0^- + \mathbf{1} \otimes \mathbf{1}$$

 Π is the analogue of I^*I . One has $\Pi X = 0 = X\Pi$.

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- Π is non-negative i.e. $\langle \Pi f, f \rangle_{L^2} \ge 0$ and Π_m is coercive i.e. $\langle \Pi_m f, f \rangle_{L^2} \ge C \|f\|_{H^{-1/2}}^2$ for all solenoidal f.
- Here, $L^2 = L^2(SM, d\mu)$, where μ is the Liouville measure.
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Stability estimates Idea of proof

- The link between I_m and Π_m is not explicit but obtained thanks to the Positive Livsic Theorem or the Approximate Livsic Theorem.
- Roughly (for some well-chosen $s \dots$) writing $\pi_m^* f = Xu + h$, with $\|h\|_{C^{\beta}} \leq \|I_m f\|_{\ell^{\infty}}^{\nu}$, one has:

$$\begin{aligned} |f||_{H^{s}} &\leq \|\Pi_{m}f\|_{H^{s+1}} \\ &= \|\pi_{m*}\Pi\pi_{m}^{*}f\|_{H^{s+1}} \\ &= \|\pi_{m*}\prod_{=0}^{N}u + \pi_{m*}\Pi h\|_{H^{s+1}} \\ &= \|\pi_{m*}\Pi h\|_{H^{s+1}} \leq \|h\|_{H^{s+1}} \leq \|I_{m}f\|_{\ell^{\infty}}^{\nu} \end{aligned}$$

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We apply the previous results in the case m = 2.

Ξ.

- (M,g) is an Anosov Riemannian manifold,
- C is the set of free homotopy classes; given c ∈ C, there exists a unique closed geodesic γ_c ∈ c (Klingenberg '74).

Definition (The marked length spectrum)

$$L_g: \left| \begin{array}{c} \mathcal{C} \to \mathbb{R}^*_+ \\ c \mapsto \ell_g(\gamma_c), \end{array} \right.$$

 $\ell_g(\gamma_c)$ Riemannian length computed with respect to g.

The marked length spectrum of a negatively-curved manifold determines the metric (up to isometries) i.e.: if g and g' have negative sectional curvature, same marked length spectrum $L_g = L_{g'}$, then there exists $\phi: M \to M$ smooth diffeomorphism such that $\phi^*g' = g$.

- The action of diffeomorphisms is a natural obstruction one cannot avoid,
- Analogue of Michel's conjecture of rigidity for simple manifolds with boundary (the boundary distance function should determine the metric up to isometries),
- Why the marked length spectrum ? The length spectrum (:= collection of lengths regardless of the homotopy) does not determine the metric (counterexamples by Vigneras '80)

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Known results:

- Croke '90, Otal '90: proof for negatively-curved surfaces,
- Katok '88: proof for g' conformal to g,
- Besson-Courtois-Gallot '95, Hamenstädt '99: proof when (M, g) is a locally symmetric space.
- Conjecture remains open in dimension > 2 for negatively-curved manifolds and in any dimension for Anosov Riemannian manifolds.

Theorem (Guillarmou-L. '18)

Let (M, g_0) be a negatively-curved manifold. Then $\exists k \in \mathbb{N}^*, \mathcal{U}$ open \mathcal{C}^k -neighborhood of g_0 such that: if $g \in \mathcal{U}$ and $L_g = L_{g_0}$, then g is isometric to g_0 .

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- Conjecture remains open in dimension > 2 for negatively-curved manifolds and in any dimension for Anosov Riemannian manifolds.

Theorem (Guillarmou-L. '18)

Let (M, g_0) be a negatively-curved manifold. Then $\exists k \in \mathbb{N}^*, \mathcal{U}$ open \mathcal{C}^k -neighborhood of g_0 such that: if $g \in \mathcal{U}$ and $L_g = L_{g_0}$, then g is isometric to g_0 .

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We pick g in a neighborhood of g_0 . Ideas of the proof:

- Solenoidal reduction: there exists a diffeomorphism $\phi : M \to M$ such that $g' := \phi^* g$ is solenoidal. (Without loss of generality, we can assume g is solenoidal at the beginning.)
- Use a Taylor expansion of the marked length spectrum:

$$\frac{L_g}{L_{g_0}} = 1 + \frac{1}{2} I_2^{g_0}(g - g_0) + \mathcal{O}(\|g - g_0\|_{C^3}^2),$$

thus, if $L_g = L_{g_0}$, $\|I_2^{g_0}(g - g_0)\|_{\ell^{\infty}} = \mathcal{O}(\|g - g_0\|_{C^3}^2).$

• Then, use the stability estimates on I_2

$$\|g - g_0\|_{H^s} \le \|I_2^{g_0}(g - g_0)\|_{\ell^\infty}^{
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We present another proof of (a refined version) this Theorem. Let us pretend we do not know the previous proof.

Theorem (Guillarmou-Knieper-L. '19)

Let (M, g_0) be a negatively-curved manifold. Then $\exists k \in \mathbb{N}^*, \mathcal{U}$ open \mathcal{C}^k -neighborhood of g_0 such that: if $g \in \mathcal{U}$ and

$$\lim_{j\to+\infty}\frac{L_g(c_j)}{L_{g_0}(c_j)}\to 1,$$

for all sequences of closed geodesics $(\gamma_{c_j})_{c \in \mathbb{N}}$ such that $L_{g_0}(c_j) \to \infty$, then g is isometric to g_0 .

For simplicity, we denote this assumption by $L_g/L_{go}
ightarrow 1.$

- The geodesic flows $(\varphi_t^{g_0})_{t \in \mathbb{R}}$ and $(\varphi_t^g)_{t \in \mathbb{R}}$ are orbit-conjugate, that is there exists a homeomorphism $\psi_g : SM \to SM$ (differentiable in the flow direction) such that $d\psi_g(X_{g_0}) = a_g X_g$,
- The marked length spectrum coincide i.e. $L_g = L_{go}$ iff the geodesic flows are conjugate i.e. $a_g \equiv 1$ (thus $\psi_g \circ \varphi_t^{go} = \varphi_t^g \circ \psi_g$),
- $d\mu_{g_0}$ is the Liouville measure induced by the metric g_0 .

Definition (Geodesic stretch)

The geodesic stretch of g with respect to the Liouville measure $\mathrm{d}\mu_{g_0}$ is

$$\mathcal{I}_{\mathrm{d}\mu_{g_0}}(g_0,g) := \int_{SM} a_g \, \mathrm{d}\mu_{g_0}$$

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Under the assumption that $L_g/L_{g_0} o 1$, $\mathcal{I}_{\mathrm{d}\mu_{g_0}}(g_0,g) = 1$.

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Lemma

Under the assumption that $L_g/L_{g_0} \to 1$, $\mathcal{I}_{\mathrm{d}\mu_{g_0}}(g_0,g) = 1$.

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Let us do some "geometry" in Met(M), the space of metrics on M.

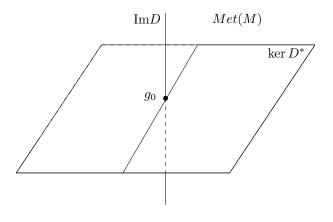
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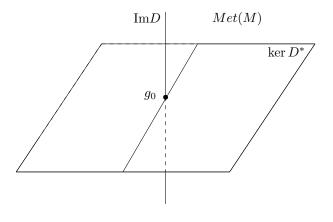
Local rigidity of the marked length spectrum Geodesic stretch

- $Met(M) \subset C^{\infty}(M, \otimes_{S}^{2}T^{*}M), \ \mathcal{O}(g_{0}) := \{\phi^{*}g_{0} \mid \phi \in \mathsf{Diff}_{0}(M)\},\$
- $T_{g_0} \operatorname{Met}(M) \simeq C^{\infty}(M, \otimes_S^2 T^*M) \simeq \ker D_{g_0}^* \oplus \operatorname{Im} D_{g_0} \simeq \ker D_{g_0}^* \oplus T_{g_0} \mathcal{O}(g_0)$

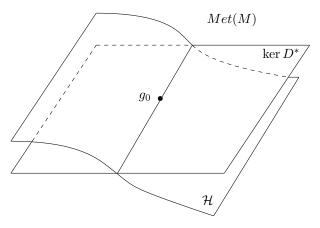


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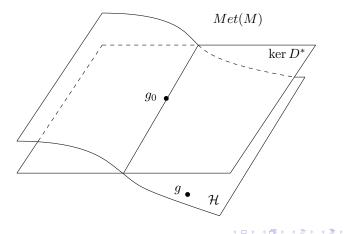


• We introduce a codimension 1 submanifold \mathcal{H} of Met(M) (defined by an implicit equation F(g) = 0 for some $F : Met(M) \to \mathbb{R}$) passing through g_0 such that $\{g \mid L_g/L_{g_0} \to 1\} \subset \mathcal{H}$. Moreover, \mathcal{H} is transverse to ker D^* .

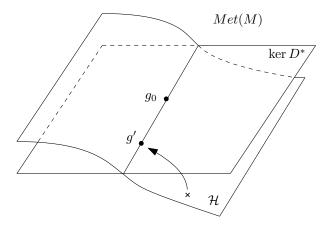


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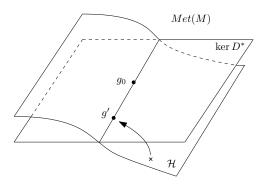
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Local rigidity of the marked length spectrum Geodesic stretch

The geodesic stretch functional $\Psi : g \mapsto \mathcal{I}_{d\mu_{g_0}}(g_0, g)$ has the following properties on $\mathcal{H} \cap \ker D^*$:

• $\Psi(g_0) = 1$

- $\mathrm{d}\Psi_{g_0} = 0$
- $\mathrm{d}^2 \Psi_{g_0}(h,h) = \mathrm{Var}_2(h) = \langle \Pi_2 h, h \rangle \ge C ||h||_{H^{-1/2}}^2$

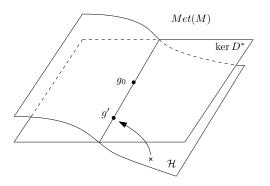


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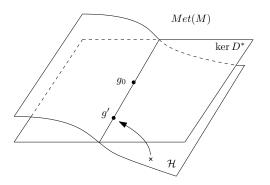


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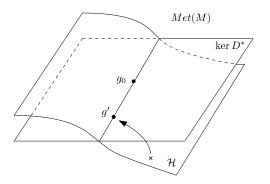


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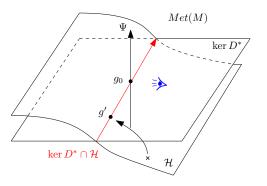


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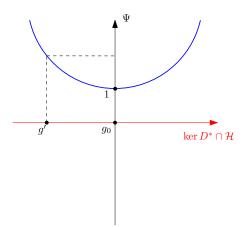
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But since $L_{g'}/L_{g_0} \rightarrow 1$, $\Psi(g') = 1$. We then easily obtain that $g' = g_0$ (as long as g was chosen close enough to g_0 at the beginning). This concludes the proof.



The proof also yields a stability estimate of the form:

Corollary

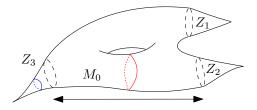
There exists $k \in \mathbb{N}$ such that for any metric $g \in \mathcal{H}$ in a neighborhood of g_0 , there exists a diffeomorphism $\phi : M \to M$ such that:

$$\|\phi^*g-g_0\|_{\mathcal{C}^k}\ \lesssim |1-\mathcal{I}_{\mathrm{d}\mu_{g_0}}(g_0,g)|$$

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Perspectives:

- Further study of the geodesic stretch functional.
- Other applications of the stability estimates on I_m , for $m \neq 0, 2$?
- Study of the Marked Length Spectrum on non-compact manifolds with hyperbolic cusps (paper in preparation with Yannick Guedes Bonthonneau).



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Thank you for your attention !

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References:

- Classical and microlocal analysis of the X-ray transform on Anosov manifolds, with Sébastien Gouëzel, in preparation,
- The marked length spectrum of Anosov manifolds, with Colin Guillarmou, preprint (https://arxiv.org/abs/1806.04218),
- Geodesic stretch and marked length spectrum rigidity, with Colin Guillarmou and Gerhard Knieper, in preparation.

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