



Mathematical
Institute

Topological defects in nematic shells: a discrete-to-continuum approach

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Workshop on Phase Transitions Models



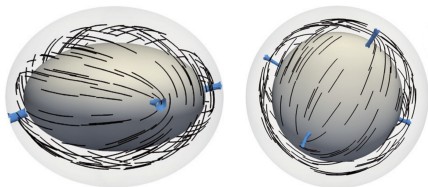
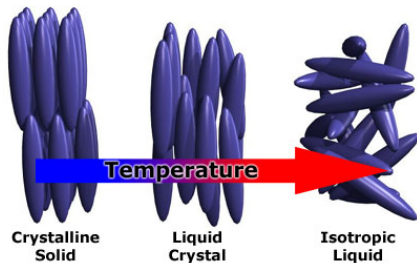
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Nematic shells

Nematic liquid crystals:
intermediate phase of matter

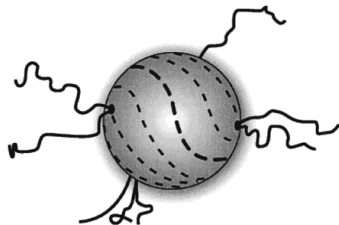
- ▷ Rod-shaped molecules
- ▷ Directional order, but no positional order



Nematic shell: small particle coated with a thin nematic film

[Figure: Bates, Skačej, Zannoni, '10]

Defects in nematic shells



The alignment of the molecules is not perfect, as **defects** arise.

[Figures: Nelson, '02; ...]

ARTICLES

PUBLISHED ONLINE: 21 SEPTEMBER 2015 | DOI: 10.1038/NMAT4421

nature
materials

Topological defects in liquid crystals as templates for molecular self-assembly

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Continuum variational models

- Smooth, compact surface $M \subseteq \mathbb{R}^3$ without boundary, with smooth unit normal $\gamma: M \rightarrow \mathbb{R}^3$.

Continuum variational models

- Smooth, compact surface $M \subseteq \mathbb{R}^3$ without boundary, with smooth unit normal $\gamma: M \rightarrow \mathbb{R}^3$.
- **Oseen-Frank** energy (in its simplest form):

$$E(\mathbf{v}) := \frac{\kappa}{2} \int_M |\nabla \mathbf{v}|^2 \, dS$$

on a space of unit-norm, tangent fields:

$$\mathcal{A}_0 := \left\{ \mathbf{v} \in W^{1,2}(M, \mathbb{R}^3) : |\mathbf{v}| = 1, \mathbf{v} \cdot \gamma = 0 \text{ a.e.} \right\}$$

$\nabla = \mathbb{R}^3$ -gradient, restricted to tangent directions

[Napoli, Vergori, '10-'12;
Segatti, Snarski, Veneroni, '14-'15...]

Is the space \mathcal{A}_0 non-empty?

The Poincaré-Hopf Theorem

For any unit-norm, tangent field \mathbf{v} on M that is smooth except at the points x_1, x_2, \dots, x_p , there holds

$$\sum_{i=1}^p \text{ind}(\mathbf{v}, x_i) = \chi(M)$$

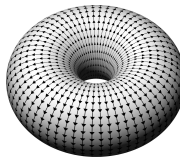
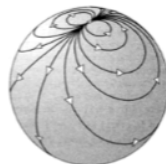
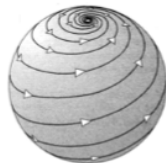
where $\chi(M)$ is the Euler characteristic, $\chi(M) = 2 - 2g$.

In particular,

$$\mathcal{A}_0 \neq \emptyset \Leftrightarrow M \simeq \mathbb{T}^2$$

Extension to Sobolev setting

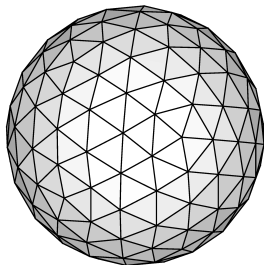
[Bethuel, '91; Brezis, Nirenberg, '95-'96;
C., Segatti, Veneroni, '15]



The XY-model

- Introduced by **Heisenberg** as a model for **spins**.
- Defects-mediated phase transition (ferromagnetism, superconductors. . .)
[Kosterlitz, Thouless, '73]
- Lattices in \mathbb{R}^n
 - Discrete-to-continuum limit (equilibrium configurations)
[Alicandro, Cicalese, '09; Alicandro, Cicalese, Ponsiglione, '14; Alicandro, De Luca, Garroni, Ponsiglione, '16. . .]
 - Dynamics **[Alicandro, De Luca, Garroni, Ponsiglione, '16. . .]**

XY-model on a surface



▷ \mathcal{T}_ε triangulation on M , $\widehat{M}_\varepsilon := \cup_{T \in \mathcal{T}_\varepsilon} T$

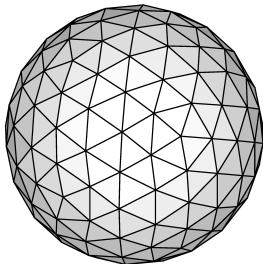
▷ $\mathcal{T}_\varepsilon^0 := \{\text{vertices of } \mathcal{T}_\varepsilon\} \subseteq M$

▷ Discrete vector fields:

$$\mathcal{A}_\varepsilon := \left\{ \mathbf{v}: \mathcal{T}_\varepsilon^0 \rightarrow \mathbb{R}^3, |\mathbf{v}(i)| = 1, \mathbf{v}(i) \cdot \boldsymbol{\gamma}(i) = 0 \right. \\ \left. \text{for any } i \in \mathcal{T}_\varepsilon^0 \right\}$$

▷ $\widehat{\mathbf{v}}: \widehat{M}_\varepsilon \rightarrow \mathbb{R}^3$ piecewise-affine interpolant

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• **Discrete energy:** for $\mathbf{v} \in \mathcal{A}_\varepsilon$,

$$XY_\varepsilon(\mathbf{v}) := \frac{1}{2} \int_{\widehat{M}_\varepsilon} |\nabla \widehat{\mathbf{v}}|^2 \, dS = \frac{1}{2} \sum_{i,j \in \mathcal{T}_\varepsilon^0} \kappa_\varepsilon^{i,j} |\mathbf{v}(i) - \mathbf{v}(j)|^2$$

Assumptions on \mathcal{T}_ε

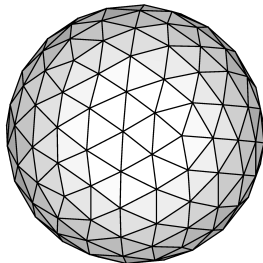
(H₁) \mathcal{T}_ε is **quasi-uniform** of size ε : for any $T \in \mathcal{T}_\varepsilon$,

$$C^{-1}\varepsilon \leq \text{diameter}(T) \leq C\varepsilon, \quad \alpha_{\min}(T) \geq C^{-1}$$

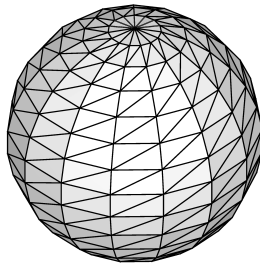
(H₂) \mathcal{T}_ε is **weakly acute**: for any $i, j \in \mathcal{T}_\varepsilon^0$ with $i \neq j$,

$$\kappa_\varepsilon^{i,j} := - \int_{\widehat{M}_\varepsilon} \nabla \widehat{\varphi}_\varepsilon^i \cdot \nabla \widehat{\varphi}_\varepsilon^j \, dS \geq 0$$

(H₃) The projection $P: \widehat{M}_\varepsilon \rightarrow M$ is well-defined and a bijection.



Allowed



Not allowed

- ▷ Due to Poincaré-Hopf Theorem,

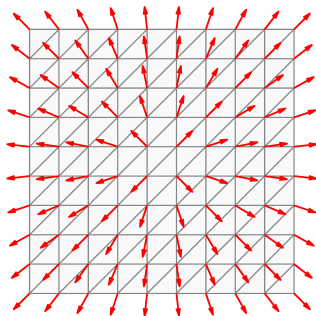
$$\inf_{\mathcal{A}_\varepsilon} XY_\varepsilon \rightarrow +\infty \quad \text{as } \varepsilon \rightarrow 0$$

unless $M \simeq \mathbb{T}^2$.

- ▷ In fact, by comparison we have

$$\inf_{\mathcal{A}_\varepsilon} XY_\varepsilon \simeq C |\log \varepsilon|$$

(discretisation of $x \mapsto x/|x|$).



- ▷ Compare with the analysis of **Ginzburg-Landau** functional [Bethuel, Brezis, Hélein, '94; Sandier, Serfaty, '07...]; [Ignat, Jerrard, '16] for the analysis on a surface.

How to detect the topological information in the discrete setting?

Jacobians of vector fields

Identify $\mathbb{R}^2 \simeq \mathbb{R}^2 \times \{0\} \subseteq \mathbb{R}^3$. For $\mathbf{u} \in C^2(\mathbb{R}^2, \mathbb{R}^2)$, we define the “pre-jacobian”

$$j^\#(\mathbf{u}) := (\mathbf{e}_3 \cdot (\mathbf{u} \times \partial_1 \mathbf{u}), \mathbf{e}_3 \cdot (\mathbf{u} \times \partial_2 \mathbf{u})), \quad \text{curl } j^\#(\mathbf{u}) = 2 \det \nabla \mathbf{u}$$

We will work in the language of differential forms:

$$j(\mathbf{u}) : \mathbf{w} \in \mathbb{R}^2 \mapsto j^\#(\mathbf{u}) \cdot \mathbf{w} = \mathbf{e}_3 \cdot (\mathbf{u} \times \nabla_{\mathbf{w}} \mathbf{u}),$$

in short $j(\mathbf{u}) = \mathbf{e}_3 \cdot (\mathbf{u} \wedge d\mathbf{u})$.

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in short $j(\mathbf{u}) = \mathbf{e}_3 \cdot (\mathbf{u} \wedge d\mathbf{u})$.

For $\mathbf{u} \in (W^{1,1} \cap L^\infty)(M, \mathbb{R}^3)$, define

$$j(\mathbf{u}) := \gamma \cdot (\mathbf{u} \wedge d\mathbf{u})$$

If \mathbf{u} is a unit-norm, tangent field, locally we can write

$$\mathbf{u} = \cos \alpha \mathbf{e}_1 + \sin \alpha \mathbf{e}_2, \quad j(\mathbf{u}) = d\alpha - \mathbf{A}$$

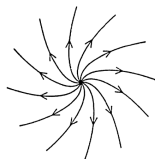
where \mathbf{A} is a smooth form that only depends on $(\mathbf{e}_1, \mathbf{e}_2)$. (Also [Ignat, Jerrard, '16])

Properties of the Jacobian

Lemma

Let $\mathbf{u} \in W^{1,1}(M, \mathbb{R}^3)$ be s.t. $|\mathbf{u}| = 1$, $\mathbf{u} \cdot \boldsymbol{\gamma} = 0$ a.e. Suppose that $\mathbf{u} \in C^2(M \setminus \{x_1, \dots, x_K\})$. Then

$$\star dJ(\mathbf{u}) = 2\pi \sum_{i=1}^K \text{ind}(\mathbf{u}, x_i) \delta_{x_i} - G dS \quad \text{in } \mathcal{D}'(M).$$

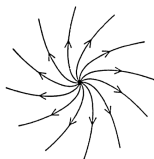


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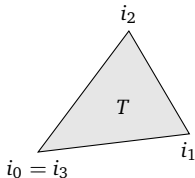


- Discrete vorticity measure:

$$\mathbf{v} \in \mathcal{A}_\varepsilon \quad \rightsquigarrow \quad \widehat{\mathbf{v}}: \widehat{M}_\varepsilon \rightarrow \mathbb{R}^3 \quad \rightsquigarrow \quad \widehat{j}_\varepsilon(\mathbf{v}) := \widehat{\boldsymbol{\gamma}}_\varepsilon \cdot (\widehat{\mathbf{v}}_\varepsilon \wedge d\widehat{\mathbf{v}}_\varepsilon)$$

$$\widehat{\mu}_\varepsilon(\mathbf{v}) := \sum_{T \in \mathcal{T}_\varepsilon} \left(\int_T d\widehat{j}_\varepsilon(\mathbf{v}) \right) \delta_{x(T)}$$

$$\widehat{\mu}_\varepsilon(\mathbf{v})[T] = \sum_{k=0}^2 \frac{\boldsymbol{\gamma}(i_k) + \boldsymbol{\gamma}(i_{k+1})}{2} \cdot \mathbf{v}(i_k) \times \mathbf{v}(i_{k+1})$$



Energetics: Leading order terms

Theorem (C., Segatti, '17)

Let $\mathbf{v}_\varepsilon \in \mathcal{A}_\varepsilon$ be such that $XY_\varepsilon(\mathbf{v}_\varepsilon) \leq C |\log \varepsilon|$.

(i) Up to subsequences, $\widehat{\mu}_\varepsilon(\mathbf{v}_\varepsilon) \xrightarrow{\text{flat}} \mu$ where

$$\mu = 2\pi \sum_{i=1}^K d_i \delta_{x_i} - G dS, \quad x_i \in M, \quad d_i \in \mathbb{Z}, \quad \sum_{i=1}^K d_i = \chi(M). \quad (\star)$$

(ii) If $\widehat{\mu}_\varepsilon(\mathbf{v}_\varepsilon) \xrightarrow{\text{flat}} \mu$ as in (\star) , then

$$\pi \sum_{i=1}^K |d_i| \leq \liminf_{\varepsilon \rightarrow 0} \frac{XY_\varepsilon(\mathbf{v}_\varepsilon)}{|\log \varepsilon|}.$$

(iii) For any μ of the form (\star) , there exist $\mathbf{v}_\varepsilon \in \mathcal{A}_\varepsilon$ such that $\widehat{\mu}_\varepsilon(\mathbf{v}_\varepsilon) \xrightarrow{\text{flat}} \mu$ and

$$\pi \sum_{i=1}^K |d_i| = \lim_{\varepsilon \rightarrow 0} \frac{XY_\varepsilon(\mathbf{v}_\varepsilon)}{|\log \varepsilon|}.$$

Here, flat = dual of C^1 .

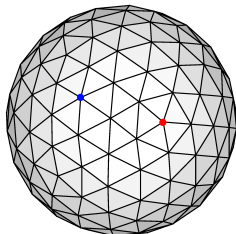
- **Warning:** in general, the sequence of fields \mathbf{v}_ε is **not** strongly precompact!
 - ▷ Role of the Jacobian — **compensated compactness**

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 - ▷ Role of the Jacobian — **compensated compactness**

- However, if \mathbf{v}_ε^* is a minimiser of XY_ε , then
 - ▷ $\mathbf{v}_\varepsilon^* \rightarrow \mathbf{v}^*$ in $W_{\text{loc}}^{1,2}(M \setminus \{x_1, \dots, x_K\}, \mathbb{R}^3)$, where $K = |\chi(M)|$
 - ▷ $\text{ind}(\mathbf{v}^*, x_i) = \text{sign}(\chi(M))$

so we control the number and local degree of defects.

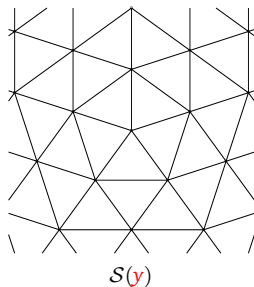
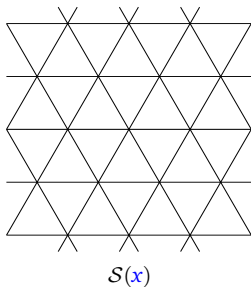
Can one characterize the position of defects?



We need an additional assumption on the sequence of triangulations, namely, for any $x \in M$ and small $\delta > 0$, there is a triangulation $\mathcal{S}(x)$ on \mathbb{R}^2 such that

$$\varphi_* (\mathcal{T}_{\varepsilon|B_\delta(x)}) \approx \varepsilon \mathcal{S}(x) \quad \text{as } \varepsilon \rightarrow 0,$$

where $\varphi: M \rightarrow T_x M \simeq \mathbb{R}^2$ are geodesic coordinates at x .



Energetics: Second-to-leading order terms

Theorem (C., Segatti, '17)

Let $K := |\chi(M)|$ and $\mathbf{v}_\varepsilon \in \mathcal{A}_\varepsilon$ be such that $XY_\varepsilon(\mathbf{v}_\varepsilon) \leq \pi K |\log \varepsilon| + C$. Then, up to subsequences, $\mathbf{v}_\varepsilon \rightarrow \mathbf{v}$ in $W_{\text{loc}}^{1,2}(M \setminus \{x_1, \dots, x_K\})$ and

$$XY_\varepsilon(\mathbf{v}_\varepsilon) = \pi K |\log \varepsilon| + \mathbb{W}(\mathbf{v}) + \sum_{i=1}^K \gamma(x_i) + o_{\varepsilon \rightarrow 0}(1).$$

▷ $\mathbb{W}(\mathbf{v}) =$ **Renormalised Energy**,

$$\mathbb{W}(\mathbf{v}) := \lim_{\delta \rightarrow 0} \left(\frac{1}{2} \int_{M_\delta} |\nabla \mathbf{v}|^2 \, dS - \pi K |\log \delta| \right)$$

where $M_\delta := M \setminus \cup_i B_\delta(x_i)$ [**Bethuel, Brezis, Hélein, '94**]

▷ $\gamma(x_i) =$ **core energy**, localised in a ball of radius $C\varepsilon$ around the defect. Depends on the triangulation

- The local properties of the triangulation may trigger the position of the defects!
≠ continuous case, uniform grid on \mathbb{R}^2
- **Question.** For $\mu = 2\pi \sum_i d_i \delta_{x_i} - \text{GdS}$, can we characterise

$$\mathbb{W}(\mu) := \inf_{\mathbf{v}: \star d_j(\mathbf{v}) = \mu} \mathbb{W}(\mathbf{v})?$$

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$$\mathbb{W}(\mu) := \inf_{\mathbf{v}: \star d_j(\mathbf{v}) = \mu} \mathbb{W}(\mathbf{v})?$$

If ∇ is replaced by covariant derivative D , we have

$$\mathbb{W}_{\text{intr}}(\mu) = 4\pi^2 \sum_{i \neq j} d_i d_j \Gamma(x_i, x_j) + 2\pi \sum_i \left(\pi d_i^2 H(x_i) - d_i V(x_i) \right) + \text{const}$$

where

$$\begin{cases} -\Delta_M \Gamma(\cdot, x_0) = \delta_{x_0} - |M|^{-1} \\ \int_M \Gamma(\cdot, x_0) dS = 0, \end{cases} \quad \begin{cases} -\Delta_M V = G - 2\pi \chi(M) |M|^{-1} \\ \int_M V dS = 0, \end{cases}$$

$$H(x_0) := \lim_{x \rightarrow x_0} \Gamma(x, x_0) + \frac{1}{2\pi} \log \text{dist}(x, x_0).$$

[Vitelli, Nelson, '04; Ignat, Jerrard, '16].

Conclusions

- Use of Jacobian: compactness + topological information
- Energetics of defects: Renormalised Energy + sensitivity to the mesh
- More physically realistic models (non-oriented models. . .) ?
- Numerics?