

# Nonuniqueness of weak solutions to the SQG equation

Steve Shkoller

UC Davis

*(Joint work with Tristan Buckmaster and Vlad Vicol)*

November 1, 2016

# The SQG equation

- ▶ Inviscid Surface Quasi-Geostrophic (SQG) equation introduced in Constantin-Majda-Tabak (1994)

$$\begin{aligned}\partial_t \theta + u \cdot \nabla \theta &= 0, \\ u &= \mathcal{R}^\perp \theta := \nabla^\perp \Lambda^{-1} \theta,\end{aligned}$$

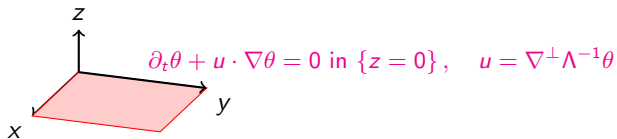
- ▶  $\theta = \theta(x, t)$ , where  $(x, t) \in \mathbb{T}^2 \times \mathbb{R} = [-\pi, \pi]^2 \times \mathbb{R}$ .
- ▶  $\Lambda = (-\Delta)^{1/2}$ ,  $\mathcal{R} = (\mathcal{R}_1, \mathcal{R}_2)$  is the vector of Riesz-transforms
- ▶  $\nabla^\perp = (-\partial_2, \partial_1)$ , and  $x^\perp = (-x_2, x_1)$  for any vector  $x = (x_1, x_2)$ .
- ▶ example of “active scalar equation”

# Geophysics

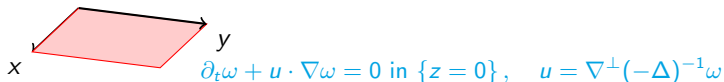
- ▶ Derivation in Held, Pierrehumbert, Garner, Swanson (1995)
- ▶  $\theta$  is temperature (or surface buoyancy)
- ▶ Model for rapidly rotating, stratified fluids
- ▶ Uniform potential vorticity
- ▶ Applications in meteorology and oceans

# SQG and 2-D Euler

- ▶ Stream function  $\psi$
- ▶ Velocity  $u = \nabla^\perp \psi$ 
  - ▶ SQG:  $-\Delta \psi = 0$  in  $\{z > 0\}$  and  $\theta = \frac{\partial \psi}{\partial z} = \Lambda \psi$ ,  $\theta = \Lambda^{-1} \psi$



- ▶ 2-D Euler:  $-\Delta \psi = \omega$  in  $\mathbb{R}^2$ , so  $\omega = (-\Delta)^{-1} \psi$



# SQG and 3-D Euler

- ▶ 3-D Euler: Let  $\omega = \text{curl } u$ 
  - ▶  $\partial_t \omega + u \cdot \nabla \omega = \nabla u \cdot \omega$
- ▶ 2-D SQG: Let  $W = \nabla^\perp \theta$ 
  - ▶  $\partial_t W + u \cdot \nabla W = \nabla u \cdot W$
- ▶ SQG has a very similar behavior as 3-D Euler
- ▶ Global existence of smooth solutions?
- ▶ Finite-time blow-up?

## A few prior results

- ▶ Local existence of smooth solutions,  $\theta_0$  in  $H^s$ ,  $s > 2$ , or  $C^{1,\alpha}$ ,  $\alpha > 0$ , Constantin-Majda-Tabak (1994)
- ▶ Numerical simulations indicated a collapsing hyperbolic saddle blow-up scenario for  $\theta$ -contours
- ▶ Cordoba (1998) and Cordoba-Fefferman (2002) ruled this out
- ▶ Constantin-Lai-Sharma-Tseng-Wu (2012) resolved numerical simulation well past predicted blow-up time

# SQG Hamiltonian and Conservation Laws

▶  $\dot{H}^{-1/2}$  Hamiltonian:

- ▶ Compute  $L^2$  inner product of SQG equation with  $\Lambda^{-1}\theta$
- ▶ integrate by parts in nonlinear term and use that  $u \cdot \nabla \Lambda^{-1}\theta = \nabla^\perp \Lambda^{-1}\theta \cdot \nabla \Lambda^{-1}\theta = 0$
- ▶ Then,

$$\mathcal{H}(t) := \|\theta(\cdot, t)\|_{\dot{H}^{-1/2}(\mathbb{T}^2)}^2 = \|\theta_0\|_{\dot{H}^{-1/2}(\mathbb{T}^2)}^2$$

- ▶ Isett-Vicol (2015) showed  $\theta \in L^3_{t,x}(\mathbb{T}^2 \times \mathbb{R})$  implies  $\mathcal{H}(t)$  conserved

▶ Casimir functions:

- ▶ Since  $\theta$  is transported by the incompressible vector field  $u$ , then

$$\|\theta(\cdot, t)\|_{L^p(\mathbb{T}^2)} = \|\theta_0\|_{L^p(\mathbb{T}^2)}, \quad 1 \leq p \leq \infty$$

# Weak solutions to inviscid SQG

▶  $L^2$  weak solution

- ▶ **Definition 1.**  $\theta \in L^2_{\text{loc}}(\mathbb{R}, L^2(\mathbb{T}^2))$  is weak solution if

$$\int \int_{\mathbb{R} \times \mathbb{T}^2} (\theta \partial_t \phi + \theta \mathbf{u} \cdot \nabla \phi) \, dx \, dt = 0 \quad \forall \phi \in C^\infty(\mathbb{T}^2 \times \mathbb{R})$$

▶ Resnick (1995) proved existence of global  $L^2$  weak solutions

▶  $\dot{H}^{-1/2}$  distributional solution

- ▶ **Definition 2.**  $\theta \in L^2_{\text{loc}}(\mathbb{R}; \dot{H}^{-1/2}(\mathbb{T}^2))$  is weak solution if

$$\int_{\mathbb{R}} \langle \mathcal{R}_i^\perp \theta, \partial_i \Lambda^{-1} \phi^i \rangle + \langle \mathcal{R}_j^\perp \theta, \mathcal{R}_i^\perp \Lambda^{-1} \theta \partial_j \phi^i \rangle - \frac{1}{2} \langle \mathcal{R}_i \mathcal{R}_j^\perp \theta, [\Lambda, \phi^i] \mathcal{R}_j^\perp \Lambda^{-1} \theta \rangle \, dt = 0$$

for any  $\phi \in C_0^\infty(\mathbb{T}^2 \times \mathbb{R})$  such that  $\text{div } \phi = 0$ , where  $\langle \cdot, \cdot \rangle$  denotes the  $\dot{H}^{-1/2}$ - $\dot{H}^{1/2}$  duality pairing.

▶ Marchand (2008) proved existence of global  $L^p$  weak solutions,  $p > 4/3$

▶  $\theta \in \dot{H}^{-1/2}$  remains open



# Nonuniqueness of weak solutions to inviscid SQG

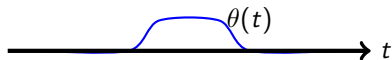
- Uniqueness remained open and was Challenge Problem 11 in De Lellis-Székelyhidi (2002), Bulletin AMS

## Theorem 1

Suppose  $\mathfrak{h} : \mathbb{R} \rightarrow \mathbb{R}^+$  is a smooth function with compact support. Then for every  $1/2 < \beta < 4/5$  and  $\sigma < \beta/(2 - \beta)$ , there exist weak solution  $\theta$ , with  $\Lambda^{-1}\theta \in C_t^\sigma C_x^\beta$ , satisfying

$$\mathcal{H}(t) = \int_{\mathbb{T}^2} \left| \Lambda^{-1/2} \theta(x, t) \right|^2 dx = \mathfrak{h}(t) \quad \forall t \in \mathbb{R}.$$

- $\theta \equiv 0$  not the only weak solution



# Dissipative SQG equation

$$\begin{aligned}\partial_t \theta + u \cdot \nabla \theta + \Lambda^\gamma \theta &= 0, \quad \gamma > 0 \\ u &= \mathcal{R}^\perp \theta := \nabla^\perp \Lambda^{-1} \theta,\end{aligned}$$

- ▶ The distribution  $\theta \in L^2_{\text{loc}}(\mathbb{R}; \dot{H}^{-1/2}(\mathbb{T}^2))$  is a weak solution of the dissipative SQG equation if

$$\begin{aligned}\int_{\mathbb{R}} \langle \mathcal{R}_i^\perp \theta, \partial_t \Lambda^{-1} \phi^i \rangle + \langle \mathcal{R}_j^\perp \theta, \mathcal{R}_i^\perp \Lambda^{-1} \theta \partial_j \phi^i \rangle \\ - \frac{1}{2} \langle \mathcal{R}_i \mathcal{R}_j^\perp \theta, [\Lambda, \phi^i] \mathcal{R}_j^\perp \Lambda^{-1} \theta \rangle - \langle \mathcal{R}_i^\perp \theta, \Lambda^{\gamma-1} \phi^i \rangle dt = 0\end{aligned}$$

for any  $\phi \in C_0^\infty(\mathbb{T}^2 \times \mathbb{R})$  such that  $\text{div } \phi = 0$ , where  $\langle \cdot, \cdot \rangle$  denotes the  $\dot{H}^{-1/2}$ - $\dot{H}^{1/2}$  duality pairing.

## Natural scaling symmetry

- ▶  $\theta_\lambda(x, t) = \lambda^{\gamma-1}\theta(\lambda x, \lambda^\gamma t)$  is a  $[-\frac{\pi}{\lambda}, \frac{\pi}{\lambda}]^2$ -periodic solution with initial datum  $\theta_{0,\lambda}(x) = \lambda^{\gamma-1}\theta_0(\lambda x)$
- ▶  $L_x^\infty$ -norm scale invariant for  $\gamma = 1$
- ▶  $\gamma > 1$  subcritical and semilinear – global regularity Constantin-Wu (1999)
- ▶  $\gamma = 1$  critical and quasilinear – global regularity Kiselev-Nazarov-Volberg (2007), Caffarelli-Vasseur (2010), Constantin-Vicol (2012)
- ▶  $\gamma < 1$  supercritical, open
- ▶  $\gamma > 0$ , weak solutions for  $\theta_0 \in \dot{H}^{-1/2}$ , Marchand (2008)

# Nonuniqueness of weak solutions to dissipative SQG

## Theorem 2

Suppose  $\mathfrak{h} : \mathbb{R} \rightarrow \mathbb{R}^+$  is a smooth function with compact support. Then for every  $1/2 < \beta < 4/5$ ,  $0 < \gamma < 2 - \beta$  and  $\sigma < \beta/(2 - \beta)$ , there exists a weak solution  $\theta$ , with  $\Lambda^{-1}\theta \in C_t^\sigma C_x^\beta$ , satisfying

$$\int_{\mathbb{T}^2} \left| \Lambda^{-1/2}\theta(x, t) \right|^2 dx = \mathfrak{h}(t) \quad \forall t \in \mathbb{R}.$$

- ▶ The restriction  $\gamma + \beta < 2$  is sharp, in the sense that the  $C_t^0 C_x^\beta$  norm for  $\Lambda^{-1}\theta$  is scale invariant when  $\gamma + \beta = 2$ .
- ▶ For supercritical scaling, parabolic smoothing does not hold.
- ▶ First instance of convex integration for subcritical semilinear equation  $1 < \gamma \leq 6/5$

# Inviscid Hydrodynamical Systems via Arnold (1966)

- ▶ Inviscid hydrodynamical systems are geodesics with respect to right invariant metrics on

$\mathcal{D}_\mu =$  group of volume-preserving diffeomorphisms

with

$$\text{metric} = \int_{\mathbb{T}^2} Au \cdot v dx, \quad A > 0 \text{ linear, self-adjoint}$$

- ▶ Apply Euler-Poincaré variational principle to find the system of PDE:

$$\partial_t v^i + \partial_j v^i u^j + \partial_i u^j v^j = -\nabla \tilde{p}$$

$$\text{div } u = 0$$

$$v = Au$$

# Reformulation of SQG

- ▶ SQG:  $A = \Lambda^{-1}$
- ▶ metric =  $\int_{\mathbb{T}^2} \Lambda^{-1} u \cdot v dx$
- ▶  $v = \Lambda^{-1} u =$  potential velocity,  $u =$  transport velocity

$$\begin{aligned} \partial_t v^i + \partial_j v^i u^j - \partial_i v^j u^j &= -\partial_i p \\ \operatorname{div} u &= 0 \\ u &= \Lambda v \end{aligned}$$

- ▶  $\theta = -\nabla^\perp v \implies \partial_t \theta + u \cdot \nabla \theta = 0$
- ▶ Very nice form for convex integration – no odd (in frequency) multiplier

# Onsager conjecture for SQG

## Conjecture 1

- (a) *If  $v \in C(\mathbb{R}; C^\alpha(\mathbb{T}^2))$  is a weak solution of the SQG equation with  $\alpha > 1$ , then the Hamiltonian is conserved. (Isett-Vicol (2015) using  $\theta$  formulation)*
- (b) *For any  $1/2 < \alpha < 1$ , there exist infinitely many weak solutions of the SQG equation, with  $v \in C(\mathbb{R}; C^\alpha(\mathbb{T}^2))$ , such that the Hamiltonian is not conserved.*

- ▶ Euler Onsager with Hölder exponent  $1/3$
- ▶ For Euler, part a) was proven by Constantin-E-Titi (1994) (cf. Eyink 1994, Cheskidov-Constantin-Friedlander- Shvydkoy 2008)
- ▶ Part b) was recently resolved:  $C_{x,t}^0$  De Lellis-Székelyhidi Jr. (2012);  $C_{x,t}^{1/10^-}$  DeSz (2012);  $C_{x,t}^{1/5^-}$  Isett (2013);  $C_{x,t}^{1/5^-}$  BuDeSz (2013);  $C_x^{1/3^-}$  a.e. in time; Bu (2015);  $L_t^1 C_x^{1/3^-}$  BuDeSz (2016); 3-D  $C_{x,t}^{1/3^-}$  Isett (2016)
- ▶ SQG regularity gap  $\alpha \in [4/5, 1)$  is similar to 2-D Euler gap  $\alpha \in [1/5, 1/3)$

# Regularity exponents

- ▶ Consider a scale of Banach spaces  $B^\alpha = C_t C_x^\alpha$

$\alpha_{WP}$  = well-posedness

$\alpha_*$  = scale invariant ,

$\alpha_U$  = uniqueness

$\alpha_O$  = Onsager scale ,

$\alpha_N$  = Nash scale .

- ▶ Expectation of ordering:  $\alpha_* \leq \alpha_O \leq \alpha_N \leq \alpha_U \leq \alpha_{WP}$  (Klainerman (2016))
- ▶ Euler:  $\alpha_{WP} = 1$ ,  $\alpha_O = 1/3$ ,  $\alpha_* = 0$ , conjectured that  $\alpha_U = 1$
- ▶ Inviscid SQG (for  $\nu$ ):  $\alpha_O = 1$ ,  $\alpha_{WP} = 2$
- ▶ Critical SQG ( $\gamma = 1$ ): Conjecture that  $1 = \alpha_* = \alpha_O = \alpha_N = \alpha_U = \alpha_{WP}$ 
  - ▶ First fluids equation where  $\alpha$  are the same!



# SQG Momentum Equation

- ▶ Strong form:  $\partial_t v^i + \partial_j v^i \Lambda v^j - \partial_i v^j \Lambda v^j + \Lambda^\gamma v^i = -\partial_i p$  with  $\operatorname{div} v = 0$
- ▶ Weak form:  $v \in L_{t,loc}^2 \dot{H}^{1/2}$  is a weak solution of SQG if

$$\int_{\mathbb{R}} \left\{ \langle v^j, \partial_t \phi^i \rangle + \langle \Lambda v^j, v^i \partial_j \phi^i \rangle + \frac{1}{2} \langle \partial_j v^i, [\Lambda, \phi^i] v^j \rangle + \int_{\mathbb{T}^2} v^i \Lambda^\gamma \phi^i dx \right\} dt = 0$$

for all  $\phi \in C_0^\infty(\mathbb{T}^2 \times \mathbb{R})$  such that  $\operatorname{div} \phi = 0$

- ▶  $L_t^\infty \dot{H}_x^{1/2}$  global weak solutions for  $v$ , Marchand (2008)

# Convex integration scheme

- ▶ We construct a sequence of solutions  $(v_q, p_q, \mathring{R}_q)$  to the *relaxed SQG momentum equation*

$$\begin{aligned} \partial_t v_q + u_q \cdot \nabla v_q - (\nabla v_q)^T \cdot u_q + \nabla p_q + \Lambda^\gamma v_q &= \operatorname{div} \mathring{R}_q \\ \operatorname{div} v_q &= 0 \\ u_q &= \Lambda v_q \end{aligned}$$

- ▶  $\mathring{R}_q$  is a symmetric trace-free  $2 \times 2$  matrix (**Reynolds stress**)
- ▶ The goal is to obtain  $\mathring{R}_q \rightarrow 0$  as  $q \rightarrow \infty$  (in a suitable topology), and show that a limiting function  $v_q \rightarrow v$  exists, and solves SQG.

# Iteration Scheme

- ▶ Iteration: **potential velocity**:  $v_{q+1} = v_q + w_{q+1}$
- ▶ Each  $v_q$  is localized at frequency  $\lambda_q$
- ▶ Given  $\lambda_0 \gg 1$ ,  $\lambda_q = \lambda_0^q$
- ▶ Each  $v_q$  has amplitude  $\lambda_0^{1-q\beta}$
- ▶ We fix  $\beta = \frac{4}{5} - \epsilon$  to be the Hölder exponent that we expect for our weak solution
- ▶ Perturbation  $w_{q+1}$  lives at frequency  $\lambda_0^{q+1}$  and must be chosen to cancel low frequency Reynolds stress  $R_q$  error, and  $|w_{q+1}| \sim \lambda_0^{1-\beta(q+1)}$

# Decomposition of Reynolds Stress error

Setting  $w_{q+1} := v_{q+1} - v_q$  we have

$$\begin{aligned}
 \operatorname{div} \mathring{R}_{q+1} &= \left( \partial_t w_{q+1} + u_q \cdot \nabla w_{q+1} \right) \\
 &\quad + \left( \Lambda w_{q+1} \cdot \nabla v_q - (\nabla v_q)^T \cdot \Lambda w_{q+1} - (\nabla u_q)^T \cdot w_{q+1} \right) \\
 &\quad + \Lambda^\gamma w_{q+1} \\
 &\quad + \left( \operatorname{div} \mathring{R}_q + \Lambda w_{q+1} \cdot \nabla w_{q+1} - (\nabla w_{q+1})^T \cdot \Lambda w_{q+1} \right) \\
 &\quad + \nabla \tilde{p}_{q+1} \\
 &=: \operatorname{div} R_T + \operatorname{div} R_N + \operatorname{div} R_D + \operatorname{div} R_O + \nabla \tilde{p}_{q+1}
 \end{aligned}$$

# Heuristic estimates for one term of Nash error

- ▶ Assume  $w_{q+1}$  is of frequency  $\sim \lambda_0^{q+1}$  and  $|w_{q+1}| \sim \lambda_0^{-\beta(q+1)}$  for  $\frac{1}{2} < \beta < 1$ , so that  $v_q \rightarrow v \in C^\beta$ .

- ▶ Then

$$\begin{aligned} \left\| \operatorname{div}^{-1} \left( (\nabla u_q)^T \cdot w_{q+1} \right) \right\|_{C^0} &\lesssim \lambda_0^{-(q+1)} \|u_q\|_{C^1} \|w_{q+1}\|_{C^0} \\ &\lesssim \lambda_0^{-(q+1)} \|v_q\|_{C^2} \|w_{q+1}\|_{C^0} \\ &\lesssim \lambda_0^{-(q+1)} \lambda_0^{q(2-\beta)} \lambda_0^{-(q+1)\beta} = \lambda_0^{(q+2)(1-2\beta)} \lambda_0^{3(\beta-1)} \end{aligned}$$

- ▶ The allowable error must be proportional to  $|\Lambda w_{q+1} \otimes w_{q+1}| \sim \lambda_0^{(q+2)(1-2\beta)}$ . Thus we obtain the restriction  $\beta < 1$ .

# The construction of $w_{q+1}$

- ▶ The perturbation will be a sum of approximate Beltrami plane waves (similar to the convex integration scheme for 2D Euler: Choffrut-De Lellis-Székelyhidi (2012), Choffrut (2012)):

$$w_{q+1} \approx \sum_k a_k(x, t) b_k(\lambda^{q+1} x)$$

- ▶ finite number of  $k = (k_1, k_1)$  in  $\mathbb{S}^1$ 
  - ▶  $k := (1, 0), (3/5, 4/5), (3/5, -4/5)$ , etc.
- ▶ Beltrami plane waves  $b_k(\xi) := ik^\perp e^{ik \cdot \xi}$  are eigenfunctions of  $\Lambda$

# The oscillation error

Recall

$$\operatorname{div} R_O = \operatorname{div} \dot{R}_q + \Lambda w_{q+1} \cdot \nabla w_{q+1} - (\nabla w_{q+1})^T \cdot \Lambda w_{q+1}$$

Setting  $w_k := a_k(x, t)b_k(\lambda^{q+1}x)$  so that  $w_{q+1} \approx \sum_k w_k$ .

$$\begin{aligned} \operatorname{div} R_O &= \operatorname{div} \dot{R}_q + \underbrace{\sum_k (\Lambda w_k \cdot \nabla w_{-k} - (\nabla w_k)^T \cdot \Lambda w_{-k})}_{\operatorname{div} R_{O,\text{low}}} \\ &\quad + \underbrace{\sum_{k+k' \neq 0} (\Lambda w_k \cdot \nabla w_{k'} - (\nabla w_k)^T \cdot \Lambda w_{k'})}_{\operatorname{div} R_{O,\text{high}}} \end{aligned}$$

It is not difficult to show that  $\operatorname{div} R_{O,\text{high}}$  is a gradient of pressure plus a small error.

# The low frequency oscillation error

We wish to write

$$\operatorname{div} \mathring{R}_q + \sum_k (\Lambda w_k \cdot \nabla w_{-k} - (\nabla w_k)^T \cdot \Lambda w_{-k}) = \operatorname{div} \left( \mathring{R}_q + \sum_k \mathcal{Q}_k \right) + \nabla \mathcal{P}_k$$

(Easy for the Euler equations, but complicated for SQG.) Setting  $\vartheta_{j,k} = \nabla^\perp \cdot w_k$ .  
With quite a bit of work, one can show

$$Q_k^{m\ell} = \mathcal{S}^m(\Lambda^{-1} \vartheta_k, \mathcal{R}^l \vartheta_{-k})$$

for some bilinear integral operator  $\mathcal{S}$ . Using the structure of  $w_k$ , expanding in frequency

$$Q_k^{m\ell} = \frac{\lambda^{q+1}}{2} |a_k|^2 k^\perp \otimes k^\perp + \text{error}.$$

(If  $a_k$  was a constant then there would be no error.)



# Transport Error

Recall

$$\operatorname{div} R_T = \partial_t w_{q+1} + u_q \cdot \nabla w_{q+1}$$

To ensure the transport error is small, we replace our previous ansatz

$$w_{q+1} \approx \sum_k a_k(x, t) b_k(\lambda^{q+1} x)$$

with

$$w_{q+1} \approx \sum_{j,k} a_{j,k}(x, t) b_k(\lambda^{q+1} \Phi_j(x, t))$$

where  $a_{j,k}(x, t)$  is zero outside the range  $(j-1)\tau_{q+1} < t < (j+1)\tau_{q+1}$  and

$$\begin{cases} \partial_t \Phi_j + u \cdot \nabla \Phi_j = 0 \\ \Phi_j(x, j\tau_{q+1}) = x. \end{cases}$$