

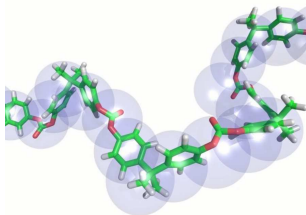
Outline

- ▶ Relative entropy, relative entropy rate, duality and bounds
- ▶ Coarse-graining & Parameterization
- ▶ Non-equilibrium steady states & Path Space Relative Entropy
- ▶ Coarse-graining & Parameterization – NESS
- ▶ Data driven coarse-graining
- ▶ Examples

Coarse-Graining – Reduced molecular models

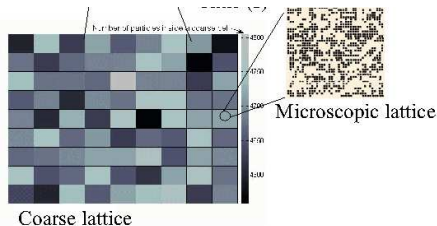
1. Coarse-graining of polymers; DPD

Briels, et. al. *J.Chem.Phys.* '01;
Müller-Plathe *Chem.Phys.Chem* '02;
Laaksonen et. al. *Soft Matter* '03;
Kremer et al. *Macromolecules* '06
Deserno et. al. *Nature* '07;
Espanol *J Chem. Phys.* '07, '11;
Shell *J. Chem. Phys.* '12;
Noid *J Chem. Phys.* '13



2. Stochastic lattice dynamics

Katsoulakis, Majda, Vlachos, *PNAS*'03;
Katsoulakis, P.P., Sopsakis, *SIAM Num. Anal.* '06;
Are, Katsoulakis, P.P., Rey-Bellet *SIAM J.Sci.Comp.* '08;
Sinno et al. *J.Chem.Phys.*'08, '13, *PRE* '12



Why information-based methods ?

Relative Entropy and \mathcal{R} -projections

- **Pseudo-distance** (Kullback-Leibler divergence)

$$\mathcal{R}(P | Q) = \int \log \left(\frac{dP}{dQ} \right) dP$$

for $P \ll R, Q \ll R$ $\mathcal{R}(P | Q) = \int p_R \log \left(\frac{p_R}{q_R} \right) dR$

Why information-based methods ?

Relative Entropy and \mathcal{R} -projections

- ▶ **Pseudo-distance** (Kullback-Leibler divergence)

$$\mathcal{R}(P | Q) = \int \log \left(\frac{dP}{dQ} \right) dP$$

for $P \ll R, Q \ll R$ $\mathcal{R}(P | Q) = \int p_R \log \left(\frac{p_R}{q_R} \right) dR$

- ▶ **Properties:** (i) $\mathcal{R}(P | Q) \geq 0$ and
(ii) $\mathcal{R}(P | Q) = 0$ iff $P = Q$ a.e.

Why information-based methods ?

Relative Entropy and \mathcal{R} -projections

- ▶ **Pseudo-distance** (Kullback-Leibler divergence)

$$\mathcal{R}(P | Q) = \int \log \left(\frac{dP}{dQ} \right) dP$$

for $P \ll R, Q \ll R$ $\mathcal{R}(P | Q) = \int p_R \log \left(\frac{p_R}{q_R} \right) dR$

- ▶ **Properties:** (i) $\mathcal{R}(P | Q) \geq 0$ and
(ii) $\mathcal{R}(P | Q) = 0$ iff $P = Q$ a.e.
- ▶ \mathcal{R} -geometry of probability distributions $\mathcal{B}(R, \rho) = \{P | \mathcal{R}(P | R) < \rho\}$
 \mathcal{R} -projection on \mathcal{A} convex, TV closed, $\mathcal{A} \cap \mathcal{B}(R, \rho) \neq \emptyset$ (Kullback, Csiszár)

$$\mathcal{R}(Q | R) = \min_{P \in \mathcal{A}} \mathcal{R}(P | R)$$

- ▶ “Geometry”: tangent hyperplane to $\mathcal{B}(R, \rho)$ at $Q, \rho = \mathcal{R}(Q | R)$

$$P \text{ s.t. } \int \log \frac{dQ}{dR} dP = \rho, \quad \mathcal{R}(P | R) = \mathcal{R}(P | Q) + \mathcal{R}(Q | R)$$

Why information-based methods ?

Relative Entropy and \mathcal{R} -projections

- ▶ **Pseudo-distance** (Kullback-Leibler divergence)

$$\mathcal{R}(P | Q) = \int \log \left(\frac{dP}{dQ} \right) dP$$

for $P \ll R, Q \ll R$ $\mathcal{R}(P | Q) = \int p_R \log \left(\frac{p_R}{q_R} \right) dR$

- ▶ **Properties:** (i) $\mathcal{R}(P | Q) \geq 0$ and
(ii) $\mathcal{R}(P | Q) = 0$ iff $P = Q$ a.e.
- ▶ The “best fit” in relative entropy: $\min_{Q \in \mathcal{A}} \mathcal{R}(P | Q)$
modeling error + numerical error + statistical error
Modelling error $\sim \mathcal{R}(P | Q) \sim \epsilon^\alpha$
Bounds on the **weak error:**

$$|\mathbb{E}_P[f] - \mathbb{E}_Q[f]| \leq C_f \Phi(\mathcal{R}(P | Q))$$

Bounding the error

modeling error

Bounding the error

modeling error + numerical error + statistical error

Bounding the error

modeling error + numerical error + statistical error

- ▶ Csiszár ϕ -divergences, convex $\phi : \mathbb{R}^+ \rightarrow \mathbb{R}$ with $\phi(1) = 0$

$$\mathcal{R}_\phi(Q | P) = \begin{cases} \int \phi\left(\frac{dQ}{dP}(\omega)\right) P(d\omega), & \text{if } Q \ll P \text{ and } \phi\left(\frac{dQ}{dP}\right) \text{ is } P\text{-integrable} \\ +\infty & \text{otherwise,} \end{cases}$$

- ▶ $\phi(x) = x \log x$ – relative entropy (Kullback-Leibler divergence)
- ▶ $\phi(x) = (x - 1)^2$ – χ^2 -divergence

Bounding the error

modeling error + numerical error + statistical error

- ▶ Csiszár ϕ -divergences, convex $\phi : \mathbb{R}^+ \rightarrow \mathbb{R}$ with $\phi(1) = 0$

$$\mathcal{R}_\phi(Q | P) = \begin{cases} \int \phi\left(\frac{dQ}{dP}(\omega)\right) P(d\omega), & \text{if } Q \ll P \text{ and } \phi\left(\frac{dQ}{dP}\right) \text{ is } P\text{-integrable} \\ +\infty & \text{otherwise,} \end{cases}$$

- ▶ $\phi(x) = x \log x$ – relative entropy (Kullback-Leibler divergence)
- ▶ $\phi(x) = (x - 1)^2 - \chi^2$ -divergence
- ▶ Csiszár-Kullback-Pinsker inequality: $\|P - Q\|_{\text{TV}} \leq \sqrt{2\mathcal{R}(P | Q)}$

$$|\mathbb{E}_P[f] - \mathbb{E}_Q[f]| \leq \|f\|_\infty \sqrt{2\mathcal{R}(P | Q)}$$

Bounding the error

modeling error + numerical error + statistical error

- ▶ Csiszár ϕ -divergences, convex $\phi : \mathbb{R}^+ \rightarrow \mathbb{R}$ with $\phi(1) = 0$

$$\mathcal{R}_\phi(Q | P) = \begin{cases} \int \phi\left(\frac{dQ}{dP}(\omega)\right) P(d\omega), & \text{if } Q \ll P \text{ and } \phi\left(\frac{dQ}{dP}\right) \text{ is } P\text{-integrable} \\ +\infty & \text{otherwise,} \end{cases}$$

- ▶ $\phi(x) = x \log x$ – relative entropy (Kullback-Leibler divergence)
- ▶ $\phi(x) = (x - 1)^2 - \chi^2$ -divergence
- ▶ Csiszár-Kullback-Pinsker inequality: $\|P - Q\|_{\text{TV}} \leq \sqrt{2\mathcal{R}(P | Q)}$

$$|\mathbb{E}_P[f] - \mathbb{E}_Q[f]| \leq \|f\|_\infty \sqrt{2\mathcal{R}(P | Q)}$$

- ▶ $\mathcal{R}(P | Q) \leq \chi^2(P | Q)$

CG: Error Quantification and Parameterization using RE in molecular simulations:

Katsoulakis, P.P. Sotasakis (2006), M.S. Shell (2008), Katsoulakis, P.P., Rey-Bellet, Tsagkarogiannis (07, 08, 09), M.S. Shell (08,12), Bilonis et al (12), Zabarar et al (13), M. Katsoulakis, P.P. (2013) (dynamics, non-equilibrium), Luskin, Simpson, Srolowitz (2015)

Variational error bounds

Error estimate of the type:

$$|\mathbb{E}_P[f] - \mathbb{E}_Q[f]| \leq C_f \Phi(\mathcal{R}(P|Q))$$

Variational representation of $\mathcal{R}(P|Q)$ and **log-moment generating function**

$$\Lambda_{P,f}(c) \equiv \frac{1}{c} \log \mathbb{E}_P[e^{cf}] = \sup_{Q \in \mathcal{P}(\Omega)} \left\{ \mathbb{E}_Q[f] - \frac{1}{c} \mathcal{R}(Q|P) \right\}$$

For $f - \mathbb{E}_P[f]$ tight variational bounds

$$\begin{aligned} \sup_{c>0} \left\{ -\frac{1}{c} \tilde{\Lambda}_{P,f}(-c) - \frac{1}{c} \mathcal{R}(Q|P) \right\} &\leq \mathbb{E}_Q[f] - \mathbb{E}_P[f] \leq \\ &\leq \inf_{c>0} \left\{ \frac{1}{c} \tilde{\Lambda}_{P,f}(c) + \frac{1}{c} \mathcal{R}(Q|P) \right\} \end{aligned}$$

Variational error bounds

Error estimate of the type:

$$|\mathbb{E}_P[f] - \mathbb{E}_Q[f]| \leq C_f \Phi(\mathcal{R}(P|Q))$$

Variational representation of $\mathcal{R}(P|Q)$ and **log-moment generating function**

$$\Lambda_{P,f}(c) \equiv \frac{1}{c} \log \mathbb{E}_P[e^{cf}] = \sup_{Q \in \mathcal{P}(\Omega)} \left\{ \mathbb{E}_Q[f] - \frac{1}{c} \mathcal{R}(Q|P) \right\}$$

For $f - \mathbb{E}_P[f]$ tight variational bounds

$$\begin{aligned} \sup_{c>0} \left\{ -\frac{1}{c} \tilde{\Lambda}_{P,f}(-c) - \frac{1}{c} \mathcal{R}(Q|P) \right\} &\leq \mathbb{E}_Q[f] - \mathbb{E}_P[f] \leq \\ &\leq \inf_{c>0} \left\{ \frac{1}{c} \tilde{\Lambda}_{P,f}(c) + \frac{1}{c} \mathcal{R}(Q|P) \right\} \end{aligned}$$

$$\inf_{c>0} \left\{ \frac{1}{c} \tilde{\Lambda}_{P,f}(c) + \frac{1}{c} \rho^2 \right\} \equiv (\tilde{\Lambda}_{P,f}^*)^{-1}(\rho^2)$$

$$\text{unique minimizer } c^*(\rho) = c_1^* \rho + \mathcal{O}(\rho^2), \quad c_1^* = \sqrt{\frac{2}{\text{Var}_P[f]}}$$

Variational error bounds

Error estimate:

$$|\mathbb{E}_P[f] - \mathbb{E}_Q[f]| \leq (\tilde{\Lambda}_{P,f}^*)^{-1}(\mathcal{R}(Q|P))$$

Asymptotics using $c^*(\rho) = \sqrt{\frac{2}{\text{Var}_P[f]}}\rho + \mathcal{O}(\rho^2)$

$$|\mathbb{E}_Q[f] - \mathbb{E}_P[f]| \leq \sqrt{\text{Var}_P[f]} \sqrt{2\mathcal{R}(Q|P)} + \mathcal{O}(\mathcal{R}(Q|P)),$$

Stability/Sensitivity estimate: $Q = P^{\theta+\epsilon}$, $P = P^\theta$

$$|\mathbb{E}_{P^{\theta+\epsilon}}[f] - \mathbb{E}_{P^\theta}[f]| \leq \sqrt{\text{Var}_{P^\theta}[f]} \sqrt{\mathbf{F}(P^\theta)} \epsilon + \mathcal{O}(|\epsilon|^2)$$

Fisher Information Matrix: $\mathbf{F}(P^\theta)_{ij} = \int \frac{\partial p_R^\theta}{\partial \theta_i} \frac{\partial p_R^\theta}{\partial \theta_j} p_R^\theta dR$

¹P. Dupuis, M. Katsoulakis, Y. Pantazis, P.P. SIAM JUQ (2016)

Path-space error estimates

- ▶ Measurable functional \mathcal{F} of the process $\{X_t\}_{t \geq 0}$

$$\begin{aligned} |\mathbb{E}_{Q_{[0,T]}}[\mathcal{F}] - \mathbb{E}_{P_{[0,T]}}[\mathcal{F}]| &\leq \sqrt{\frac{1}{T} \text{Var}_{P_{[0,T]}}[T\mathcal{F}]} \sqrt{\frac{2}{T} \mathcal{R}(Q_{[0,T]} | P_{[0,T]})} \\ &\quad + \mathcal{O}\left(\frac{1}{T} \mathcal{R}(Q_{[0,T]} | P_{[0,T]})\right) \end{aligned}$$

Path-space error estimates

- ▶ Measurable functional \mathcal{F} of the process $\{X_t\}_{t \geq 0}$

$$\begin{aligned} |\mathbb{E}_{Q_{[0,T]}}[\mathcal{F}] - \mathbb{E}_{P_{[0,T]}}[\mathcal{F}]| &\leq \sqrt{\frac{1}{T} \text{Var}_{P_{[0,T]}}[T\mathcal{F}]} \sqrt{\frac{2}{T} \mathcal{R}(Q_{[0,T]} | P_{[0,T]})} \\ &\quad + \mathcal{O}\left(\frac{1}{T} \mathcal{R}(Q_{[0,T]} | P_{[0,T]})\right) \end{aligned}$$

- ▶ Stationary process ($T \rightarrow \infty$)

$$\frac{1}{T} \mathcal{R}(Q_{[0,T]} | P_{[0,T]}) = \mathcal{H}(q | p) + \frac{1}{T} \mathcal{R}(\mu | \nu)$$

$$|\mathbb{E}_{Q_{[0,T]}}[\mathcal{F}] - \mathbb{E}_{P_{[0,T]}}[\mathcal{F}]| \leq \sqrt{\frac{1}{T} \text{Var}_{P_{[0,T]}}[T\mathcal{F}]} \sqrt{2\mathcal{H}(q | p) + \frac{2}{T} \mathcal{R}(\mu | \nu)} + \text{h.o.t.}$$

Coarse-graining non-equilibrium systems

- ▶ focus on systems with steady states
- ▶ Non-equilibrium steady state (NESS) \neq const. $e^{-\beta H(\sigma)}$
 - ▶ systems driven by external fields, boundary conditions etc.
 - ▶ reaction networks
 - ▶ polymer flows
 - ▶ heterogeneous reaction systems with multiple mechanisms: reaction-diffusion-adsorption-desorption
- ▶ Find the “best-fit” coarse-grained Markovian approximation possibly non-Markovian – estimate memory kernels in Mori-Zwanzig formalism.

Non-equilibrium steady states

Example: Continuous-time jump process (KMC)

$$\partial_t P(\sigma, t; \zeta) = \sum_{\sigma'} [c(\sigma', \sigma) P(\sigma', t; \zeta) - c(\sigma, \sigma') P(\sigma, t; \zeta)] ,$$

Stationary states: $\partial_t P = 0 \implies \sum_{\sigma'} \mathbf{j}_s(\sigma', \sigma) = 0$

Current $\sigma' \rightarrow \sigma$: $\mathbf{j}_s(\sigma', \sigma) = c(\sigma', \sigma)\mu(\sigma') - c(\sigma, \sigma')\mu(\sigma)$

Reversible dynamics with the equilibrium $\mu(\sigma)$

Detailed Balance condition with respect to $\mu(\sigma)$ (e.g., $\mu \sim e^{-\beta H(\sigma)}$)

$$c(\sigma', \sigma)\mu(\sigma') = c(\sigma, \sigma')\mu(\sigma)$$

Irreversible dynamics \implies Non-equilibrium steady states

$$\sum_{\sigma'} \mathbf{j}_s(\sigma', \sigma) = \sum_{\sigma'} (c(\sigma', \sigma)\mu(\sigma') - c(\sigma, \sigma')\mu(\sigma)) = 0$$

irreversible rate loops, i.e., a non-zero current at stationary states.

Relative entropy on the path space

- ▶ Markov chains on Σ :
 $\{\sigma_n\}_{n \in \mathbb{Z}^+}$, $P^\theta(\sigma, d\sigma)$, $\mu^\theta(\sigma)$
- ▶ Approximating Markov chain $\{\tilde{\sigma}_n\}_{n \in \mathbb{Z}^+}$, $\tilde{P}^\theta(\sigma, d\sigma)$, $\tilde{\mu}^\theta(\sigma)$
- ▶ Path measures:

$$Q^\theta(\sigma_0, \dots, \sigma_M) = \mu^\theta(\sigma_0) p^\theta(\sigma_0, \sigma_1) \dots p^\theta(\sigma_{M-1}, \sigma_M)$$

- ▶ Radon-Nikodym derivative

$$\frac{dQ^\theta}{d\tilde{Q}^\theta}(\{\sigma_n\}) = \frac{\mu^\theta(\sigma_0) \prod_{i=0}^{M-1} p^\theta(\sigma_i, \sigma_{i+1})}{\tilde{\mu}^\theta(\sigma_0) \prod_{i=0}^{M-1} \tilde{p}^\theta(\sigma_i, \sigma_{i+1})}$$

- ▶ Relative entropy

$$\mathcal{R}(Q^\theta | \tilde{Q}^\theta) = \int_{\Sigma^M} \mu^\theta(\sigma_0) \prod_{i=0}^{M-1} p^\theta(\sigma_i, \sigma_{i+1}) \log \frac{\mu^\theta(\sigma_0) \prod_{i=0}^{M-1} p^\theta(\sigma_i, \sigma_{i+1})}{\tilde{\mu}^\theta(\sigma_0) \prod_{i=0}^{M-1} \tilde{p}^\theta(\sigma_i, \sigma_{i+1})} d\sigma$$

Relative entropy decomposition and scaling

$$\begin{aligned} \mathcal{R} \left(Q^\theta \mid \tilde{Q}^\theta \right) &= \int_{\Sigma} \cdots \int_{\Sigma} \mu^\theta(\sigma_0) \prod_{i=0}^{M-1} p^\theta(\sigma_i, \sigma_{i+1}) \left(\log \frac{\mu^\theta(\sigma_0)}{\tilde{\mu}^\theta(\sigma_0)} \right. \\ &\quad \left. + \sum_{i=0}^{M-1} \log \frac{p^\theta(\sigma_i, \sigma_{i+1})}{\tilde{p}^\theta(\sigma_i, \sigma_{i+1})} \right) d\sigma_0 \cdots d\sigma_M \end{aligned}$$

Relative entropy decomposition and scaling

$$\begin{aligned} \mathcal{R} \left(Q^\theta \mid \tilde{Q}^\theta \right) &= \int_{\Sigma} \cdots \int_{\Sigma} \mu^\theta(\sigma_0) \prod_{i=0}^{M-1} p^\theta(\sigma_i, \sigma_{i+1}) \left(\log \frac{\mu^\theta(\sigma_0)}{\tilde{\mu}^\theta(\sigma_0)} \right. \\ &\quad \left. + \sum_{i=0}^{M-1} \log \frac{p^\theta(\sigma_i, \sigma_{i+1})}{\tilde{p}^\theta(\sigma_i, \sigma_{i+1})} \right) d\sigma_0 \dots d\sigma_M \end{aligned}$$

Using

$$\begin{aligned} \int_{\Sigma} p(\sigma, \sigma') d\sigma' &= 1, \quad \int_{\Sigma} \mu(\sigma) p(\sigma, \sigma') d\sigma = \mu(\sigma') \\ \int_{\Sigma} \mu^\theta(\sigma_0) \log \frac{\mu^\theta(\sigma_0)}{\tilde{\mu}^\theta(\sigma_0)} d\sigma_0 &+ \sum_{i=0}^{M-1} \int_{\Sigma} \int_{\Sigma} \mu^\theta(\sigma_i) p^\theta(\sigma_i) \log \frac{p^\theta(\sigma_i, \sigma_{i+1})}{\tilde{p}^\theta(\sigma_i, \sigma_{i+1})} \\ &= M \mathbb{E}_{\mu}^{\theta} \left[\int_{\Sigma} p^\theta(\sigma, \sigma') \log \frac{p^\theta(\sigma, \sigma')}{\tilde{p}^\theta(\sigma, \sigma')} d\sigma' \right] + \mathcal{R}(\mu^\theta \mid \tilde{\mu}^\theta) \end{aligned}$$

Relative entropy decomposition and scaling

$$\begin{aligned} \mathcal{R}(Q^\theta | \tilde{Q}^\theta) &= \int_{\Sigma} \cdots \int_{\Sigma} \mu^\theta(\sigma_0) \prod_{i=0}^{M-1} p^\theta(\sigma_i, \sigma_{i+1}) \left(\log \frac{\mu^\theta(\sigma_0)}{\tilde{\mu}^\theta(\sigma_0)} \right. \\ &\quad \left. + \sum_{i=0}^{M-1} \log \frac{p^\theta(\sigma_i, \sigma_{i+1})}{\tilde{p}^\theta(\sigma_i, \sigma_{i+1})} \right) d\sigma_0 \dots d\sigma_M \end{aligned}$$

Using

$$\begin{aligned} \int_{\Sigma} p(\sigma, \sigma') d\sigma' &= 1, \quad \int_{\Sigma} \mu(\sigma) p(\sigma, \sigma') d\sigma = \mu(\sigma') \\ \int_{\Sigma} \mu^\theta(\sigma_0) \log \frac{\mu^\theta(\sigma_0)}{\tilde{\mu}^\theta(\sigma_0)} d\sigma_0 &+ \sum_{i=0}^{M-1} \int_{\Sigma} \int_{\Sigma} \mu^\theta(\sigma_i) p^\theta(\sigma_i) \log \frac{p^\theta(\sigma_i, \sigma_{i+1})}{\tilde{p}^\theta(\sigma_i, \sigma_{i+1})} \\ &= M \mathbb{E}_{\mu}^{\theta} \left[\int_{\Sigma} p^\theta(\sigma, \sigma') \log \frac{p^\theta(\sigma, \sigma')}{\tilde{p}^\theta(\sigma, \sigma')} d\sigma' \right] + \mathcal{R}(\mu^\theta | \tilde{\mu}^\theta) \end{aligned}$$

$$\mathcal{R}(Q^\theta | \tilde{Q}^\theta) = M \mathcal{H}(Q^\theta | \tilde{Q}^\theta) + \mathcal{R}(\mu^\theta | \tilde{\mu}^\theta)$$

Continuous time Markov chain

$\mathcal{D}_{[0,T]}$ (resp. $\tilde{\mathcal{D}}_{[0,T]}$) is the distribution of the process $\{\sigma_t\}_{t \in [0,T]}$ (resp. $\{\tilde{\sigma}_t\}_{t \in [0,T]}$) on the path space $\mathcal{Q}([0, T], \Sigma_N)$

$$\mathcal{R} \left(\mathcal{D}_{[0,T]} \mid \tilde{\mathcal{D}}_{[0,T]} \right) = \int \log \left(\frac{d\mathcal{D}_{[0,T]}}{d\tilde{\mathcal{D}}_{[0,T]}} \right) d\mathcal{D}_{[0,T]},$$

The initial distribution is **the stationary measure** μ (resp. $\tilde{\mu}$).

Radon-Nikodym derivative:

$$\frac{d\mathcal{D}_{[0,T]}}{d\tilde{\mathcal{D}}_{[0,T]}} = \frac{\mu(\sigma_0)}{\tilde{\mu}(\sigma_0)} \exp \left\{ - \int_0^T [\lambda(\sigma_s) - \tilde{\lambda}(\sigma_s)] ds + \int_0^T \log \frac{c(\sigma_{s-}, \sigma_s)}{\tilde{c}(\sigma_{s-}, \sigma_s)} dN_s \right\}$$

$$\mathcal{R} \left(\mathcal{D}_{[0,T]} \mid \tilde{\mathcal{D}}_{[0,T]} \right) = T\mathcal{H}(\mathcal{D}_{[0,T]} \mid \tilde{\mathcal{D}}_{[0,T]}) + \mathcal{R}(\mu \mid \tilde{\mu})$$

Langevin dynamics

- ▶ Microscopic dynamics with forcefield $x \in \mathbb{R}^n \mapsto b(x) \in \mathbb{R}^n$, $\text{rank } \sigma(x) \leq n$

$$dX_t = b(X_t)dt + \sigma(X_t)dB_t, \quad t \geq 0, \quad X_0 \sim \mu_0.$$

- ▶ Approximating dynamics

$$d\tilde{X}_t = \tilde{b}(\tilde{X}_t; \theta)dt + \sigma(\tilde{X}_t)dB_t, \quad t \geq 0, \quad \tilde{X}_0 \sim \nu_0,$$

- ▶ Radon-Nikodym derivative

$$\frac{dP_X^{[0, T]}}{dP_{\tilde{X}}^{[0, T]}}(X_t, t) = \frac{d\mu_0}{d\nu_0}(X_0) \exp \left\{ - \int_0^t \langle u(X_s; \theta), dB_s \rangle - \frac{1}{2} \int_0^t |u(X_s; \theta)|^2 ds \right\}.$$

$$\sigma(X_s)u(X_s; \theta) = b(X_s) - \tilde{b}(X_s; \theta)$$

- ▶ Relative entropy

$$\mathcal{R}(P_X^T | P_{\tilde{X}}^T) = \mathbb{E}_{P_X^T} \left[\int_0^T \frac{1}{2} |u(X_s; \theta)|^2 ds \right] + \mathcal{R}(\mu_0 | \nu_0)$$

Relative entropy rate

For stationary process: $\mathcal{R}(P_X^T | P_{\tilde{X}}^T) = T\mathcal{H}(P_X^T | P_{\tilde{X}}^T) + \mathcal{R}(\mu_0 | \nu_0)$

$$\mathcal{H}(P_X^T | P_{\tilde{X}}^T) = \lim_{T \rightarrow \infty} \frac{1}{T} \mathcal{R}(P_X^T | P_{\tilde{X}}^T)$$

- ▶ RER representation for stationary process

$$\mathcal{H}(P_X | P_{\tilde{X}}) = \mathbb{E}_{\mu} \left[\frac{1}{2} \|b(X) - \tilde{b}(X; \theta)\|_{\Xi}^2 \right],$$

the norm $\|\cdot\|_{\Xi}$ defined by $\Xi(x) = [\sigma^T(x)\sigma(x)]^{-1} \sigma^T(x)$.

- ▶ RE representation for finite time

$$\mathcal{R}(P_X^T | P_{\tilde{X}}^T) = \mathcal{H}^T(P_X^T | P_{\tilde{X}}^T) + \mathcal{R}(\mu_0 | \nu_0),$$

where

$$\mathcal{H}^T(P_X^T | P_{\tilde{X}}^T) = \mathbb{E}_{P_X^T} \left[\frac{1}{2} \int_0^T \|b(X_s) - \tilde{b}(X_s; \theta)\|_{\Xi}^2 ds \right].$$

Relative Entropy Rate and Dynamics Parametrization

Langevin dynamics

- ▶ CG map: $\mathbb{R}^n \rightarrow \mathbb{R}^m$, $x \mapsto \bar{x} = \mathbf{T}x$
- ▶ CG Markovian dynamics

$$d\bar{X}_t = \bar{b}(\bar{X}_t; \theta) dt + \bar{\sigma}(\bar{X}_t; \theta) d\bar{B}_t, \quad \bar{X}_0 \sim \bar{\mu}_0$$

- ▶ Reconstructed process $\mathbf{T}\tilde{X}_t = \bar{X}_t$ in distribution

$$d\tilde{X}_t = \tilde{b}(\tilde{X}_t; \theta) dt + \tilde{\sigma}(\tilde{X}_t; \theta) dB_t, \quad \tilde{X}_0 \sim \nu_0$$

$$\begin{aligned} \mathbf{T}\tilde{b}(x; \theta) &= \bar{b}(\mathbf{T}x; \theta), & \mathbf{T}\tilde{\Sigma}(x; \theta)\mathbf{T}^T &= \bar{\Sigma}(\mathbf{T}x; \theta) \text{ for all } x \in \mathbb{R}^n \\ \tilde{\Sigma}(x; \theta) &= \tilde{\sigma}(x; \theta)\tilde{\sigma}^T(x; \theta), & \bar{\Sigma}(\bar{x}; \theta) &= \bar{\sigma}(\bar{x}; \theta)\bar{\sigma}^T(\bar{x}; \theta) \end{aligned}$$

- ▶ Best fit at stationary regime – minimize \mathcal{H}

$$\min_{\theta \in \Theta} \mathbb{E}_\mu \left[\frac{1}{2} \|\mathbf{T}b(X) - \bar{b}(\mathbf{T}X; \theta)\|_{\mathbf{T}^\# \Xi}^2 \right]$$

$$\text{new metric } \|\bar{b}\|_{\mathbf{T}^\# \Xi} \equiv \bar{b}^T \mathbf{T}^\#, T \Xi^T \Xi \mathbf{T}^\# \bar{b}, \quad \mathbf{T}^\# \equiv \mathbf{T}^T (\mathbf{T} \mathbf{T}^T)^{-1}.$$

¹Kalligianaki, Harmandaris, Katsoulakis, P.P. (2016)

Relative Entropy Rate and Dynamics Parametrization

Lattice KMC dynamics

- ▶ Define parametrized CG transition probabilities $q^{\theta^*}(\sigma, \sigma')$:
 - ▶ Parametrized CG transition probabilities $\bar{p}^{\theta}(\eta, \eta')$
 - ▶ Reconstruction scheme: $\nu(\sigma' | \mathbf{T}\sigma')$, e.g. uniform: $\frac{1}{|\{\sigma: \mathbf{T}\sigma = \eta'\}|}$
 - ▶ $q^{\theta}(\sigma, \sigma') = \nu(\sigma' | \mathbf{T}\sigma') \bar{p}^{\theta}(\mathbf{T}\sigma, \mathbf{T}\sigma')$,
- ▶ $\mathcal{R}(P | Q^{\theta}) =$ **Loss of Information (in time-series) due to CG**
- ▶ For long times $M \gg 1$, **RER** is dominant:

$$\mathcal{R}(P | Q^{\theta}) = M\mathcal{H}(P | Q^{\theta}) + \mathcal{R}(\mu | \mu^{\theta})$$

$$\mathcal{H}(P | Q^{\theta}) = \sum_{\sigma \in \Sigma} \mu(\sigma) \sum_{\sigma' \in \Sigma} p(\sigma, \sigma') \log \frac{p(\sigma, \sigma')}{q^{\theta}(\sigma, \sigma')}].$$

- ▶ No need for explicit knowledge of NESS: suitable for reaction networks, driven systems, reaction-diffusion, etc.

Cramer-Rao inequalities for time-series

Identifiability and pFIM

- ▶ a biased estimator $\hat{\theta} = f(X)$ of the parameter θ with bias function $\psi(\theta)$
 $\mathbb{E}_{P^\theta}[f] = \psi(\theta)$

Cramer-Rao inequality

$$\text{Var}_{P^\theta}(\hat{\theta}) \geq \frac{[\psi'(\theta)]^2}{\mathbf{F}(P^\theta)}$$

- ▶ a new Cramer-Rao type inequality for time series stationary statistics
 $\hat{\theta} = \mathcal{F}_T(X)$ with the path-space observables such as $\mathcal{F}_T(X) = \frac{1}{T} \sum_i f(X_i)$

$$\tau_{P^\theta}(f) \geq \frac{[\psi'(\theta)]^2}{\mathbf{F}_{\mathcal{H}}(P^\theta)}$$

where $\psi(\theta) = \mathbb{E}_{P_{[0,T]}^\theta}[\mathcal{F}_T]$ is the bias of the estimator.

Inverse Dynamic Monte Carlo

- ▶ Best-fit obtained by minimizing RER

$$\theta^* = \arg \min_{\theta} \mathcal{H}(P | Q^{\theta}),$$

- ▶ Optimality condition $\nabla_{\theta} \mathcal{H}(P | Q^{\theta}) = 0$; minimization scheme:

$$\theta^{(n+1)} = \theta^{(n)} - \frac{\alpha}{n} G^{(n+1)},$$

$\alpha > 0$ and $G^{(n+1)}$ being a suitable approximation of the gradient $\nabla_{\theta} \mathcal{H}(P | Q^{\theta})$

- ▶ FIM revisited-**Newton-Raphson**:

$$G^n = \text{Hess}(\mathcal{H}(P | Q^{\theta^n}))^{-1} \nabla_{\theta} \mathcal{H}(P | Q^{\theta^n}).$$

$$\mathbf{F}_{\mathcal{H}}(Q^{\theta}) = \text{Hess}(\mathcal{H}(P | Q^{\theta})) = -\mathbb{E}_{\mu} \left[\sum_{\sigma'} p(\sigma, \sigma) \nabla_{\theta}^2 \log q^{\theta}(\sigma, \sigma') \right].$$

Examples: Statistical estimators

$$\mathcal{H}(\mathcal{D}_{[0,T]} | \tilde{\mathcal{D}}_{[0,T]}^\theta) = \mathbb{E}_\mu \left[\sum_{\sigma'} c(\sigma, \sigma') \log \frac{c(\sigma, \sigma')}{\tilde{c}(\sigma, \sigma'; \theta)} - (\lambda(\sigma) - \tilde{\lambda}(\sigma; \theta)) \right]$$

Estimator I:

$$\hat{\mathcal{H}}_1^{(n)} = \frac{1}{T} \sum_{k=0}^{n-1} \delta\tau_k \left[\sum_{\sigma'} c(\sigma_k, \sigma') \log \frac{c(\sigma_k, \sigma')}{\tilde{c}(\sigma_k, \sigma')} - (\lambda(\sigma_k) - \tilde{\lambda}(\sigma_k)) \right]$$

Estimator II:

$$\hat{\mathcal{H}}_2^{(n)} = \frac{1}{n} \sum_{k=0}^{n-1} \log \frac{c(\sigma_k, \sigma_{k+1})}{\tilde{c}(\sigma_k, \sigma_{k+1})} - \frac{1}{T} \sum_{k=0}^{n-1} \delta\tau_k (\lambda(\sigma_k) - \tilde{\lambda}(\sigma_k))$$

¹Pantazis, Katsoulakis J. Chem. Phys. (2013)

Data-based parametrization of CG dynamics

- ▶ Unbiased estimator for RER,

$$\hat{\mathcal{H}}_N(P|Q^\theta) := \frac{1}{N} \sum_{i=1}^N \log \frac{p(\sigma_i, \sigma_{i+1})}{q^\theta(\sigma_i, \sigma_{i+1})},$$

- ▶ Minimization of RER:

$$\min_{\theta} \hat{\mathcal{H}}_N(P|Q^\theta) = \max_{\theta} \frac{1}{N} \sum_{i=1}^N \log q^\theta(\sigma_i, \sigma_{i+1}) - \frac{1}{N} \sum_{i=1}^N \log p(\sigma_i, \sigma_{i+1}),$$

- ▶ *Coarse-grained path space log-likelihood maximization*

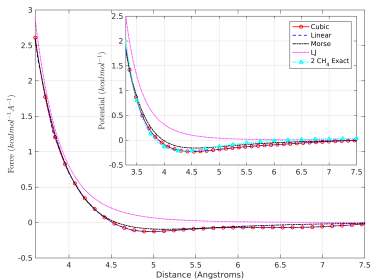
$$\max_{\theta} \ell(\theta; \{\sigma_i\}_{i=0}^N) := \max_{\theta} \frac{1}{N} \sum_{i=1}^N \log \bar{p}^\theta(\mathbf{T}\sigma_i, \mathbf{T}\sigma_{i+1}).$$

- ▶ No need for microscopic reconstruction: $q^\theta(\sigma, \sigma') = \nu(\sigma'|\mathbf{T}\sigma')\bar{p}^\theta(\mathbf{T}\sigma, \mathbf{T}\sigma')$

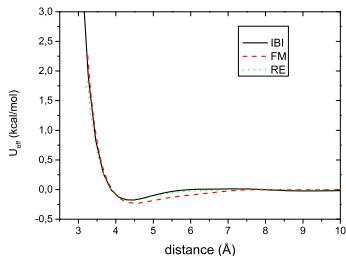
Examples

Bulk methane liquid at equilibrium (NVT)

- ▶ CG: CH₄ in one-site representation with a pair potential (non-bonded only)
- ▶ micro scale: $T = 100K$, 512 CH₄ molecules, $\rho = 0.38g/cm^3$



(a) Dynamic force matching scheme derived potential.

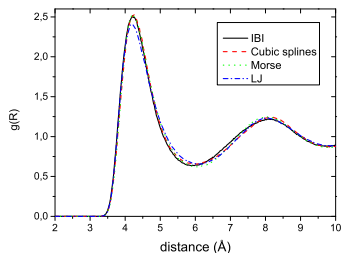


(b) CG effective potentials approximated from different methods

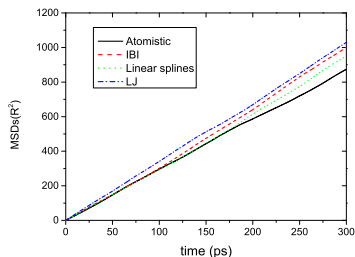
Examples

Bulk methane liquid at equilibrium (NVT)

- ▶ CG: CH₄ in one-site representation with a pair potential (non-bonded only)
- ▶ micro scale: $T = 100K$, 512 CH₄ molecules, $\rho = 0.38g/cm^3$



(c) CG pair correlation function.

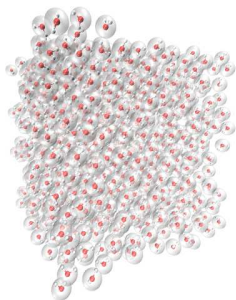


(d) Mean square displacement.

Examples

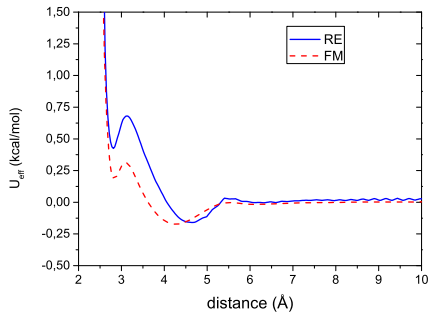
Water

- ▶ CG: H₂O in one-site representation with a pair potential (non-bonded only)
- ▶ micro scale: $T = 300K$, $p = 1\text{atm}$, 1192 H₂O molecules, SPC/E force-field



(e) Snap shot of micro scale simulation

Petr Plecháč (UDEL)



(f) CG effective interactions

Examples

Driven Arrhenius diffusion

- ▶ Rates: Exchange dynamics with the migration rate to n.n. site $|x - y| = 1$

$$c(x, y, \sigma) = d e^{-\beta(U(x, \sigma))} [\sigma(x)(1 - \sigma(x + 1)) + \sigma(x)(1 - \sigma(x - 1))]$$

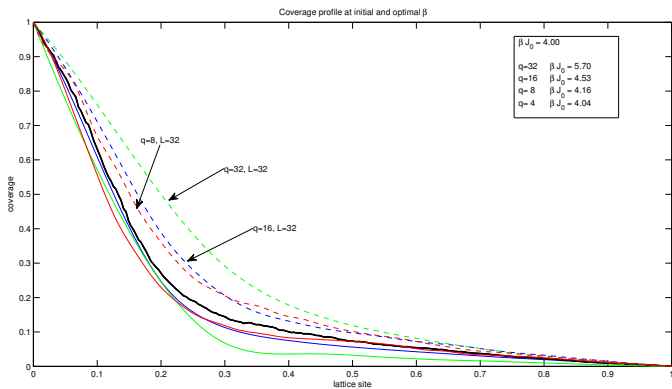
- ▶ Energy barrier: $U(x, \sigma) = \sum_{z \neq x} J(x - z)\sigma(z) - h$
 $J(z) = J_0$, for $|z| \leq L$ and $J = 0$ otherwise.
- ▶ Parametrized coarse-grained potential:

$$\bar{U}(k, \eta) = \sum_l \bar{J}(k, l)\eta(k) + \bar{J}(0, 0)(\eta(k) - 1) - \bar{h}$$

- ▶ Coarse-grained rates: assume *local equilibrium*, $\sigma(x) \approx q^{-1}\eta(k)$

$$\bar{c}(k, l, \eta) = \frac{1}{q}\eta(k)(q - \eta(l)) d e^{-\beta\bar{U}(k, \eta)}$$

- ▶ $\theta = (\beta\bar{J}_0, \bar{J}(k, l), \bar{J}(k, l, m) \dots)$



Stationary concentration profile from CG dynamics with fitted rates using $\theta = \beta \bar{J}_0$

