

Robustness of Complex Networks: Reaching Consensus Despite Adversarial Agents

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Standard Consensus Dynamics

- ▶ Network: n nodes $\{x_1, x_2, \dots, x_n\}$, edge set E
- ▶ Each node x_i starts with a real number $x_i[0]$
- ▶ **Linear averaging dynamics:**

$$x_i[k+1] = w_{ii}x_i[k] + \sum_{j \in \text{nbr}(i)} w_{ij}x_j[k]$$

- ▶ As long as the network is **connected:**

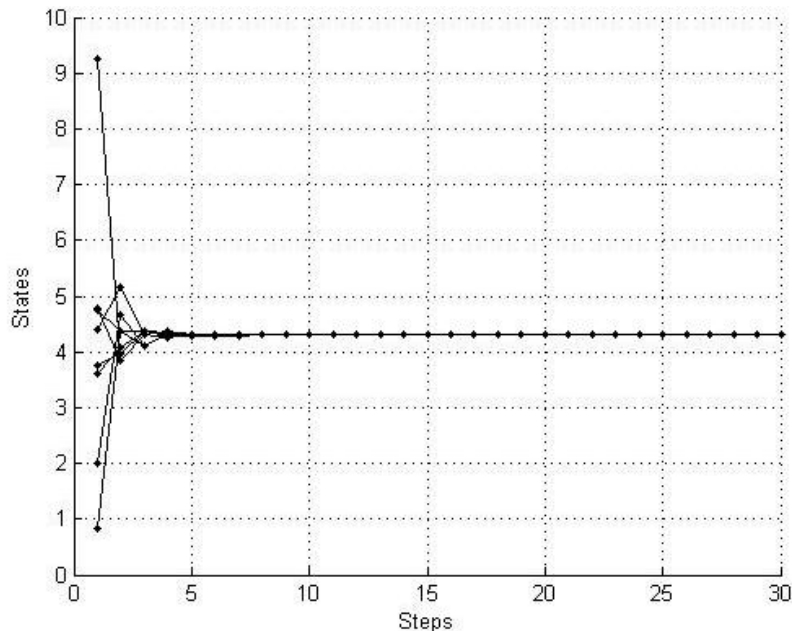
$$\lim_{k \rightarrow \infty} x_i[k] = \sum_{i=1}^n \alpha_i x_i[0], \quad \forall i \in \{1, 2, \dots, n\}$$

- ▶ The coefficients α_i are nonnegative and sum to 1

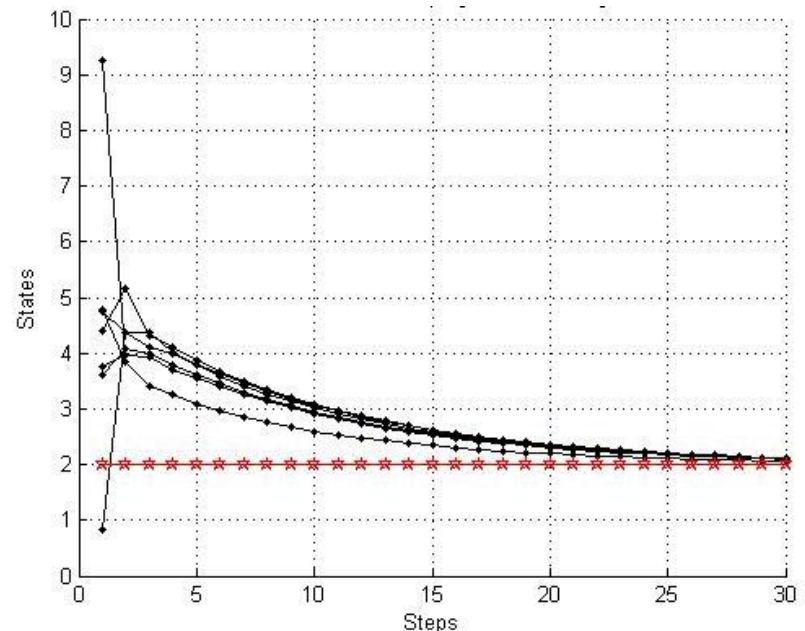
Potential for Adversarial Behavior

- ▶ What happens if some nodes **don't follow** the averaging dynamics?
- ▶ Example: suppose some node keeps its value **constant**

No adversaries



One stubborn adversary



Resilient Consensus Objective

- ▶ Node set partitioned into two sets: **N (normal nodes)** and **A (adversarial nodes)**
 - ▶ Sets N and A are unknown to normal nodes
 - ▶ Adversarial nodes are allowed to update their states arbitrarily
 - ▶ Normal nodes follow whatever dynamics we propose
- ▶ Consider the following (relaxed) objective:

“All normal nodes should asymptotically reach consensus on some value that is between the smallest and largest initial values of the normal nodes”
- ▶ Adversarial nodes should not be able to bias the consensus value **excessively**

Local Filtering

- ▶ Natural strategy: Each normal node is “suspicious” of extreme values in its neighborhood
- ▶ Mechanism:
 - ▶ At each time-step k , each node x_i receives values from its neighbors
 - ▶ x_i **removes the F highest and F lowest values** in its neighborhood, updates its state as a convex combination of remaining values

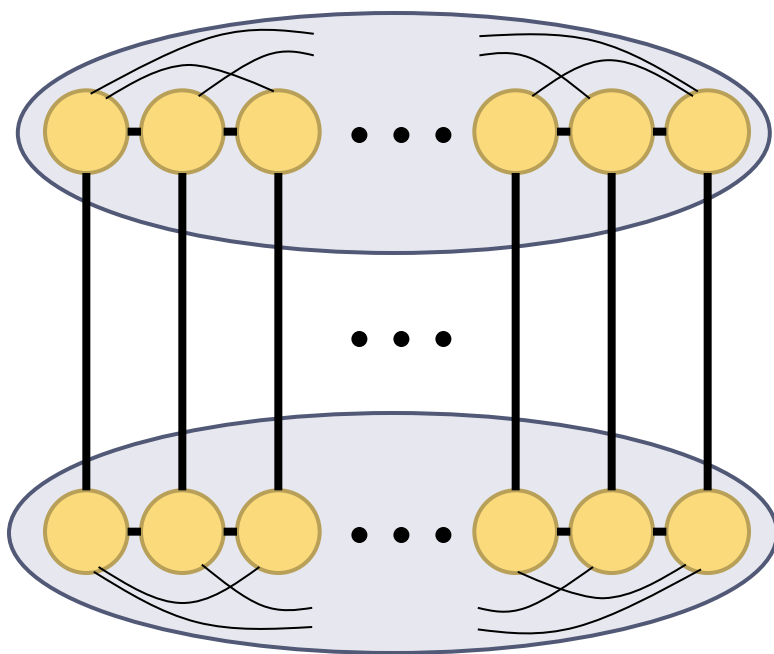
$$x_i[k + 1] = w_{ii}x_i[k] + \sum_{j \in \overline{\text{nbr}}(i)} w_{ij}x_j[k]$$

← Neighbors after removing extreme values

- ▶ F is a parameter indicating level of suspicion

Convergence

- ▶ Traditional graph metrics not useful to characterize convergence



Fully-connected graph with $n/2$ nodes
Initial value 0

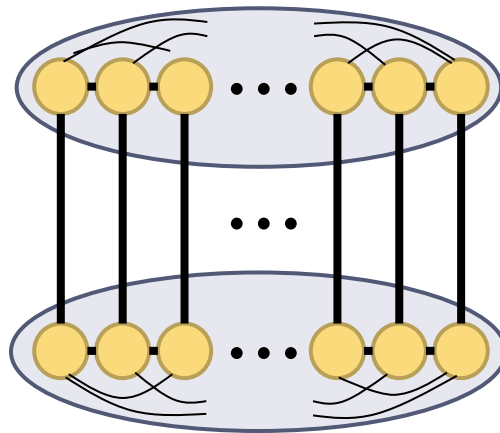
One-to-one edges between sets

Fully-connected graph with $n/2$ nodes
Initial value 1

- ▶ Connectivity of graph is $n/2$, but **no node ever uses a value from opposite set**

Insufficiency of Connectivity as a Metric

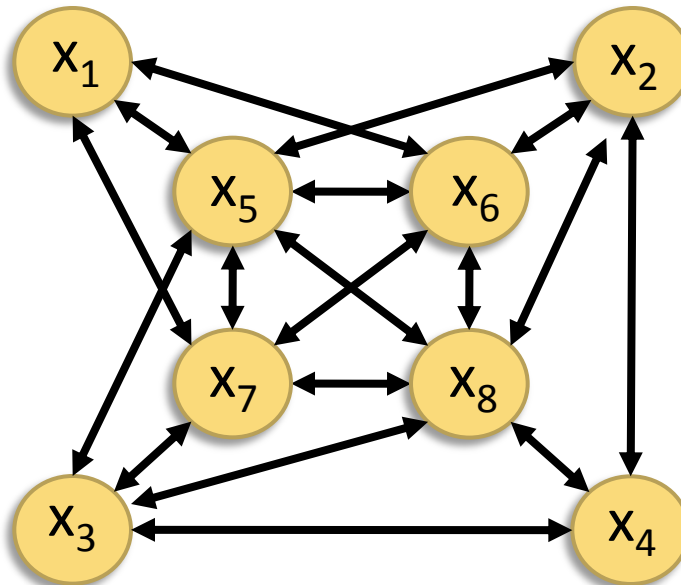
- ▶ **Connectivity is no longer a sufficient metric** to characterize behavior of purely local filtering mechanism
 - ▶ Graph contains sets where no node in any set has **enough neighbors** outside the set
 - ▶ i.e., all outside information is filtered away by each node



- ▶ **Need a new topological property** to characterize conditions under which local filtering will succeed

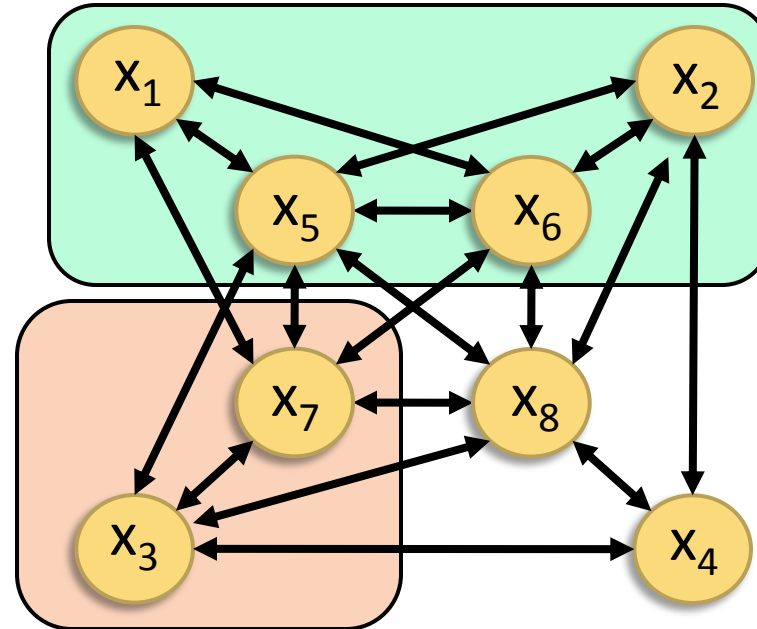
Robust Graphs

- ▶ We introduce the following definitions
 - ▶ A set S is **r -reachable** if it has a node that has at least r neighbors outside the set



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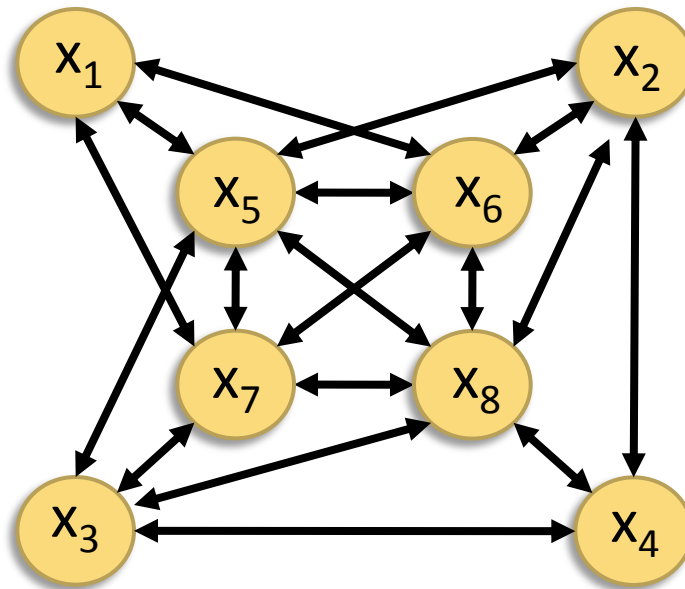


A 3-reachable set

A 4-reachable set

Robust Graphs

- ▶ A graph is **r -robust** if for any two disjoint subsets, at least one of the sets is r -reachable

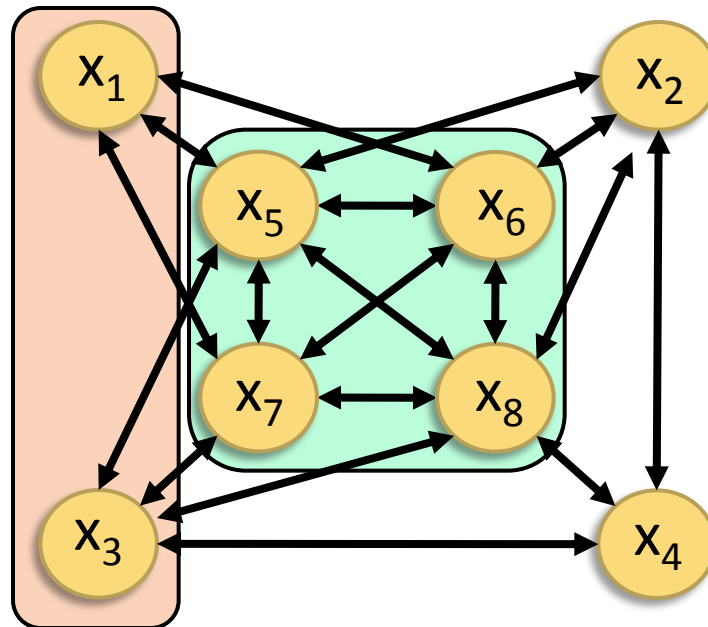


3-robust graph:

Pick any two subsets of nodes, at least one is 3-reachable

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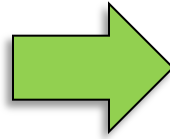
3-robust graph:

Pick any two subsets of nodes, at least one is 3-reachable

The Role of Robustness in Convergence

- ▶ **Main result:** If there are at most F adversarial nodes

Graph is **$(2F+1)$ -robust**



Normal nodes will reach consensus despite actions of adversarial nodes

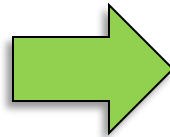
- ▶ **Robustness is the key metric** for purely local filtering/diffusion mechanisms
- ▶ Recall: Can construct graphs that have very high connectivity ($n/2$), but that are only 1-robust
- ▶ Question: What is the robustness of “complex networks”?
 - ▶ Will purely local filtering mechanisms work on these networks?

Erdos-Renyi Graphs

- ▶ Erdos-Renyi graphs $G(n, p(n))$: Define

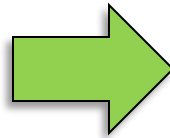
$$p(n) = \frac{\ln(n) + (r - 1) \ln \ln(n) + c(n)}{n}$$

If $c(n) \rightarrow -\infty$ as
 $n \rightarrow \infty$



$G(n, p(n))$ almost surely has
**min degree, connectivity and
robustness less than r** as $n \rightarrow \infty$

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Phase Transition for Erdos-Renyi Graphs

▶ **Threshold function:**

$$t(n) = \frac{\ln(n) + (r - 1) \ln \ln(n)}{n}$$

- ▶ ER graph experiences a phase transition for r -min degree, r -connectivity and r -robustness at this threshold
- ▶ There is a “triple jump” at this threshold [Zhang & Sundaram, CDC 2012]
- ▶ “Double jump” for min degree and connectivity known since [Erdos & Renyi, 1961]

Geometric Random Graphs

- ▶ For 1-d geometric graphs, we show:

If graph is $\left(\frac{3}{2}r\right)$ -connected, then it is at least r -robust

- ▶ **Key point:** highly connected 1-d geometric random graphs are also highly robust

Preferential Attachment Networks

- ▶ One option to model graphs that grow over time:
Preferential Attachment process
- ▶ Start with a small group of nodes
- ▶ At each time-step, a new node comes in and attaches to r existing nodes (Barabasi-Albert model)
 - ▶ Key point: prefer to attach to nodes that have a large degree
 - ▶ Produces a power law network
- ▶ If initial network is r -robust, we show:

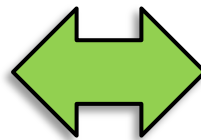
Resulting Power-Law graph is r -connected and r -robust

Thanks!
(Come see poster for more details!)

Connectivity as a Metric for Robustness

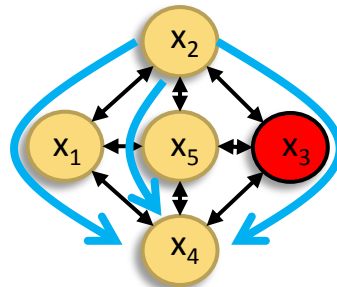
- ▶ Traditional result: In fixed networks with **up to F adversaries**:

Network has at least $2F+1$



Any two nodes can reliably exchange initial values despite actions of F adversarial nodes

- ▶ Note: adversaries allowed to update their states **arbitrarily**



- ▶ Requires normal nodes to know the entire network to route/decode information to/from other nodes