

Population Cycles and Habitat Fragmentation

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Collaborators

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Predator-Prey Models

Lotka-Volterra

$$\frac{dN}{dt} = rN - \alpha NP$$

$$\frac{dP}{dt} = \chi NP - \delta P$$

Rosenzweig-MacArthur

$$\frac{dN}{dt} = rN \left(1 - \frac{N}{k}\right) - \frac{\alpha NP}{N + \mu}$$

$$\frac{dP}{dt} = \frac{\chi NP}{d + N} - \delta P$$

May

$$\frac{dN}{dt} = rN \left(1 - \frac{N}{k}\right) - \frac{\alpha NP}{N + \mu}$$

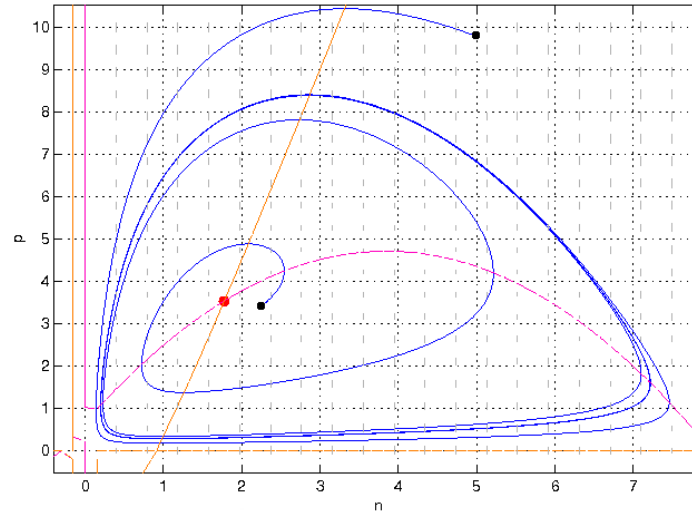
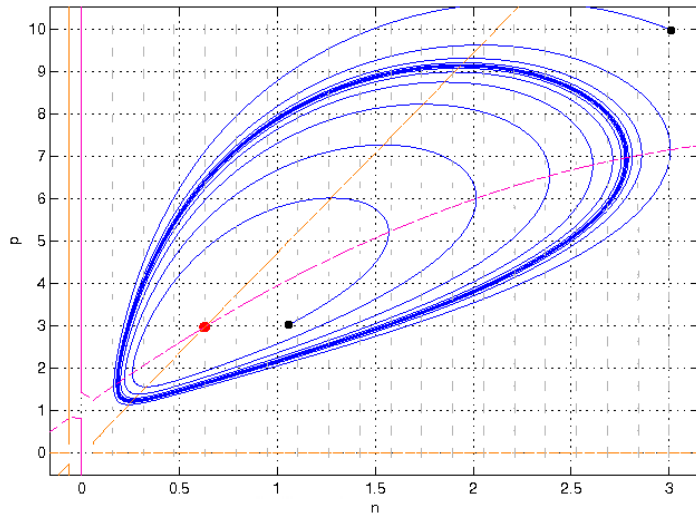
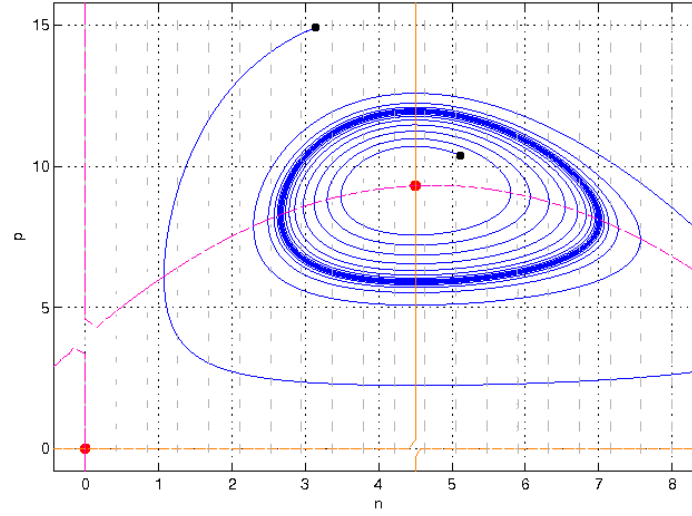
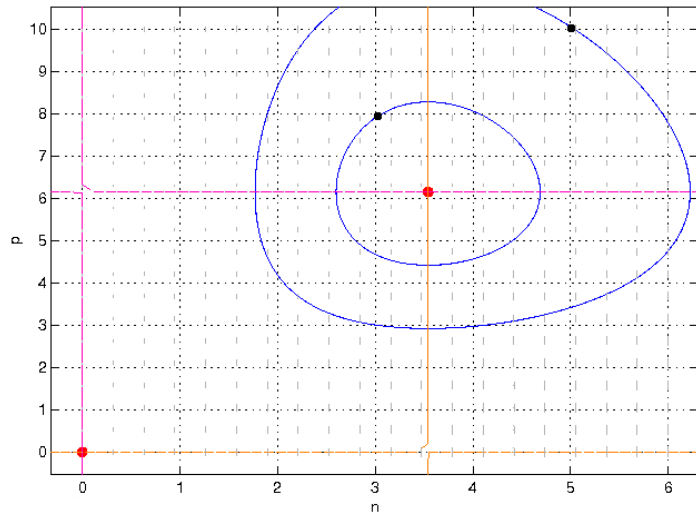
$$\frac{dP}{dt} = sP \left(1 - \frac{qP}{N}\right)$$

Variable Territory

$$\frac{dN}{dt} = rN \left(1 - \frac{N}{k}\right) - \frac{\alpha NP}{N + \mu}$$

$$\frac{dP}{dt} = \frac{\chi NP}{d + N} - \delta P - \frac{sqP^2}{N}$$

Predator-Prey Phase Planes



Spatial Model

$$\frac{\partial n}{\partial t} = D_n \frac{\partial^2 n}{\partial x^2} + f(n, p, x), \quad (1a)$$

$$\frac{\partial p}{\partial t} = D_p \frac{\partial^2 p}{\partial x^2} + g(n, p), \quad (1b)$$

where,

n, p = the prey & predator population densities,

D_n, D_p = the diffusivity coefficients,

$f(n, p, x), g(n, p)$ = the reaction terms.

Habitat Fragmentation

Combined Separation and Loss



Increasing
 Decreasing
 Domain Size Constant

Habitat Loss



Constant
 Decreasing

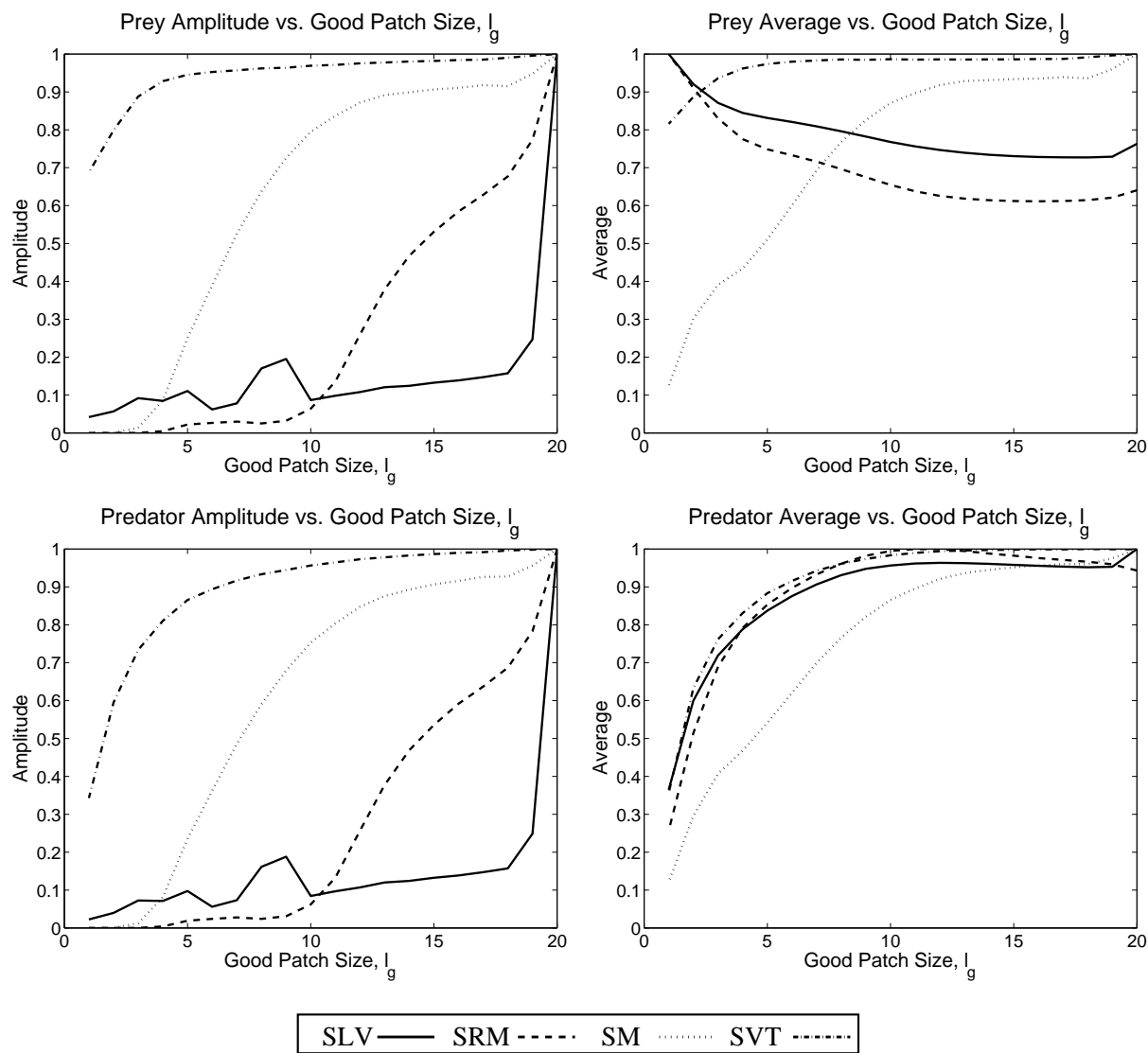
Domain Size Decreasing

Habitat Separation

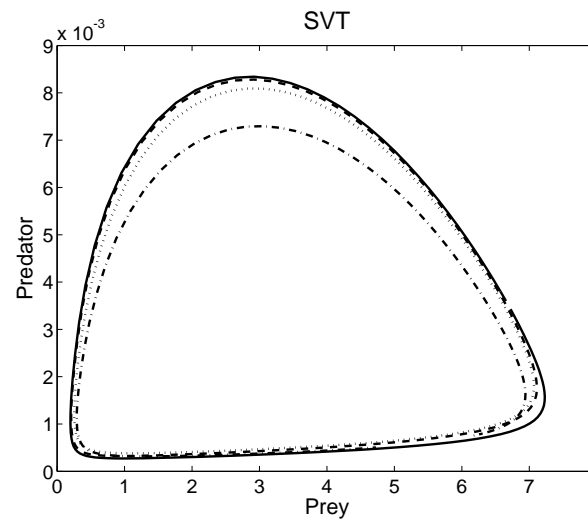
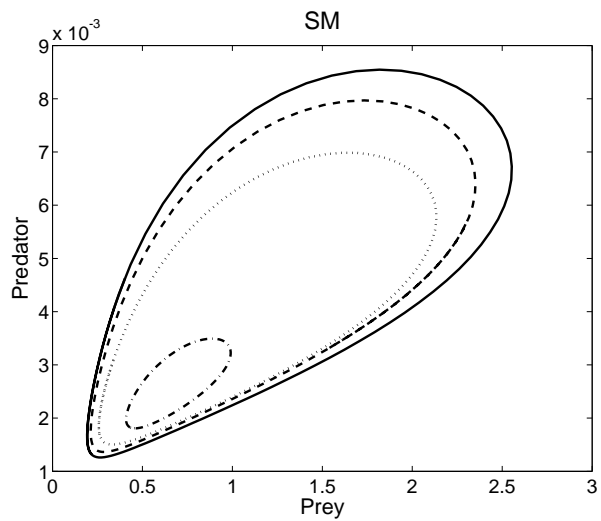
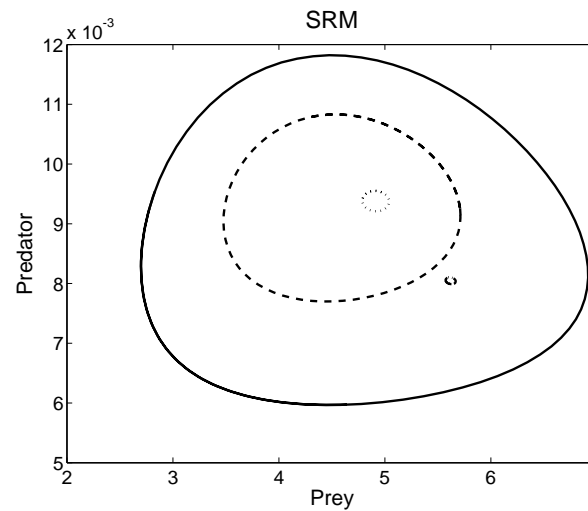
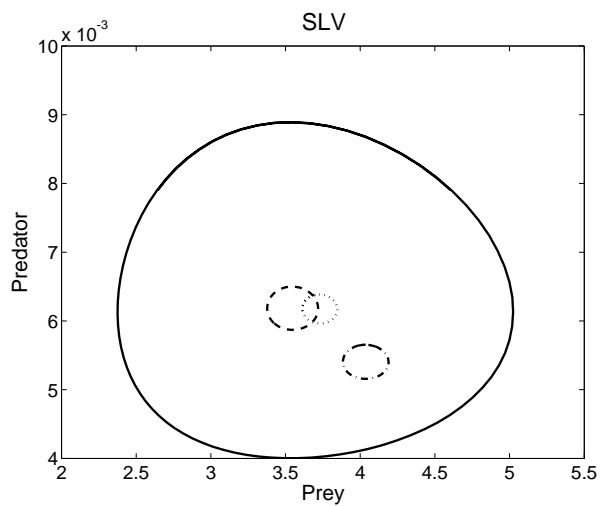


Increasing
 Constant
 Domain Size Increasing

Cycles on Two-Patch Domains

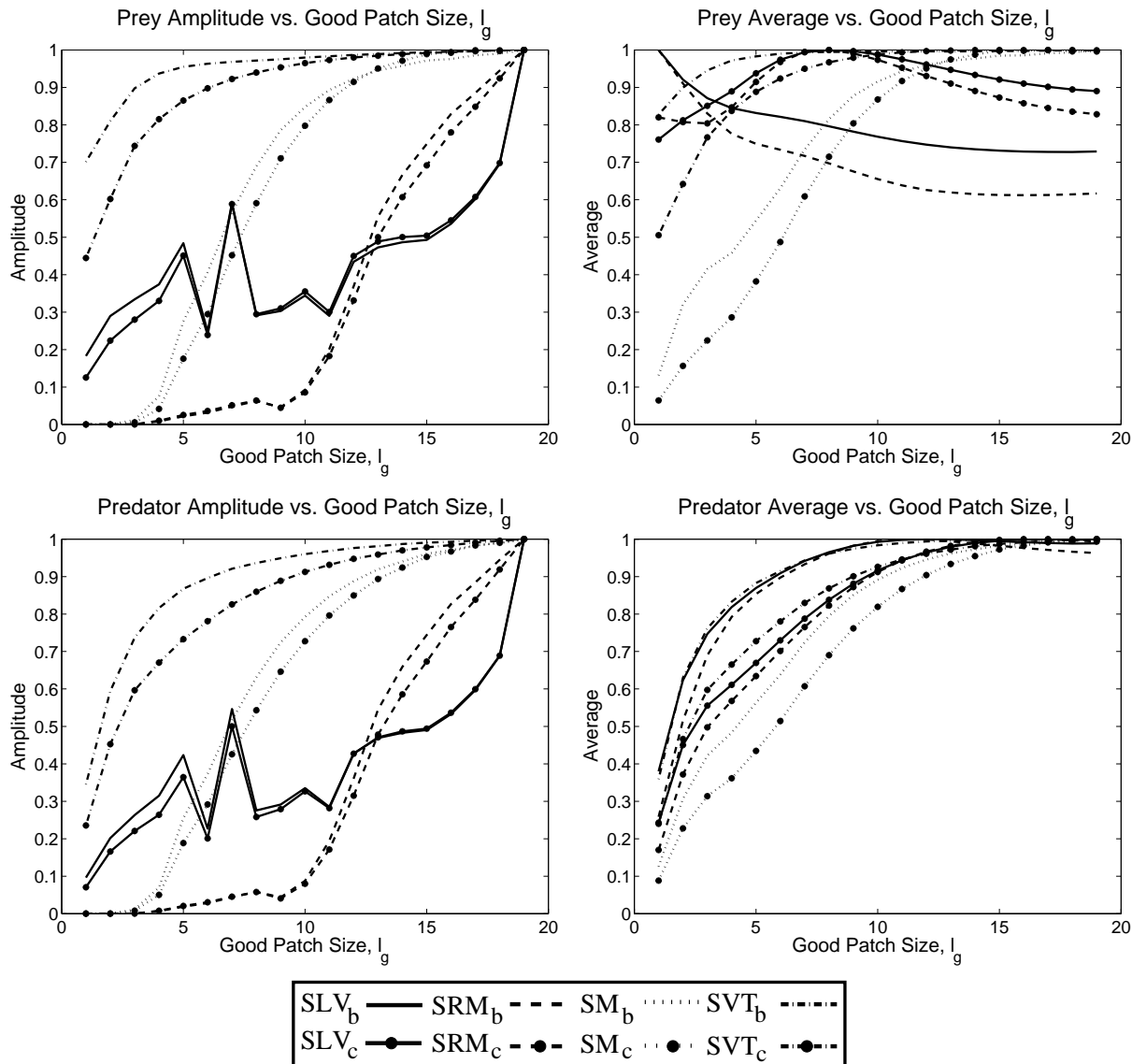


Phase Planes on Two-Patch Domains



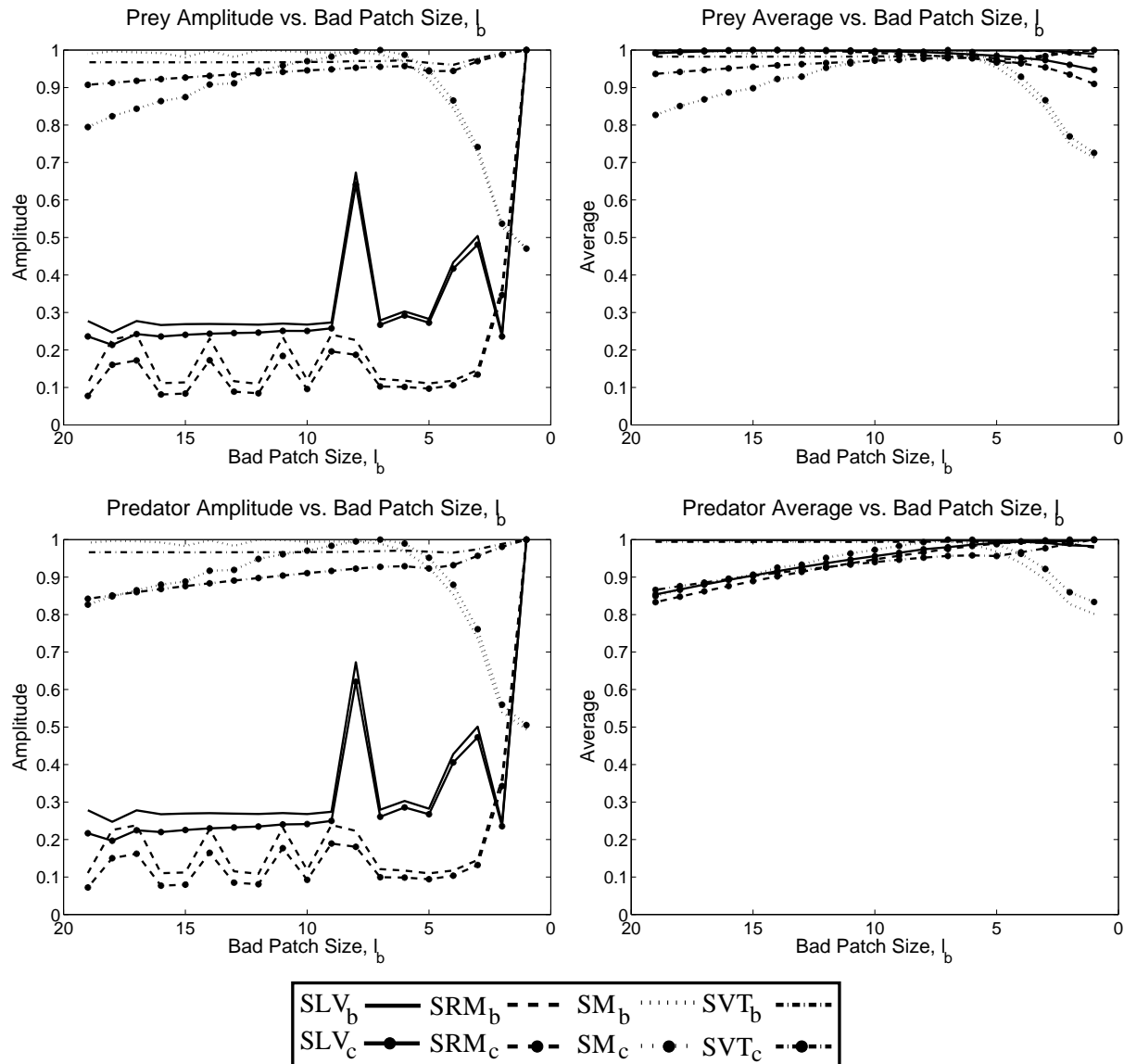
20g — 15g - - - - 10g 5g - - - -

Habitat Loss - Four-Patch Domain



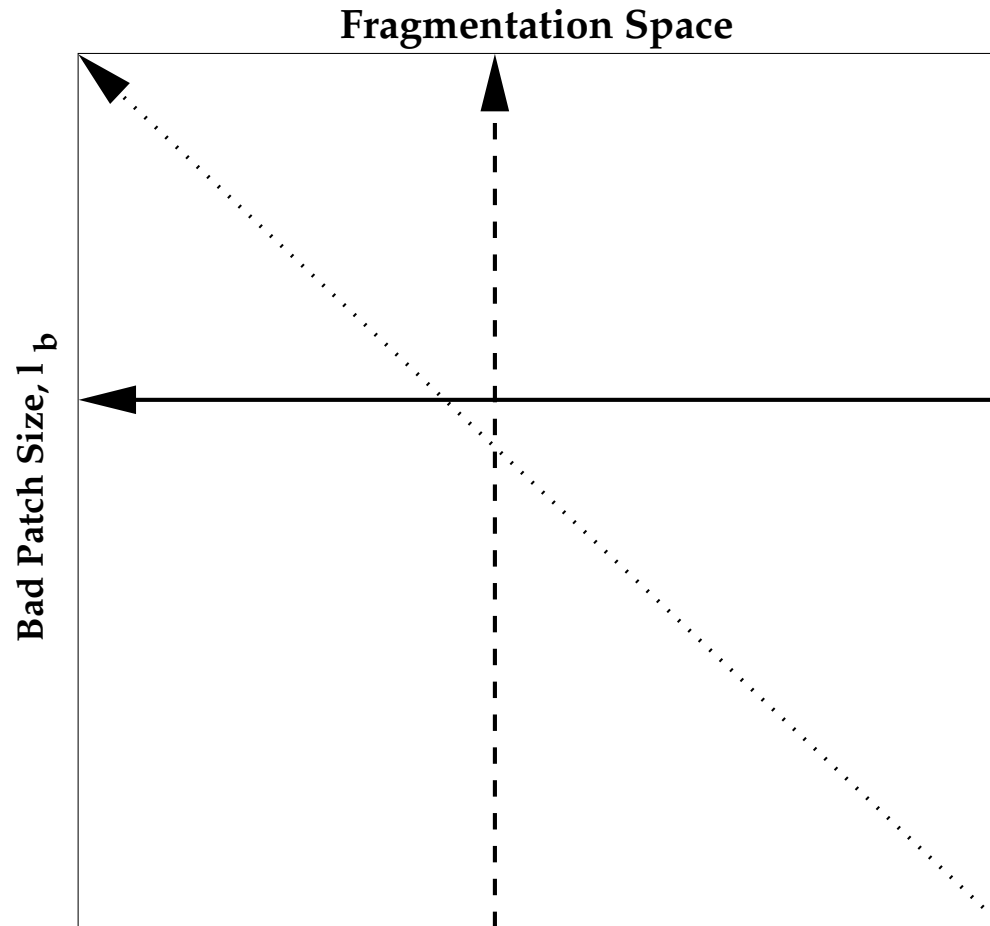
Domain: $n_g = n_b = 2$, $l_b = 12$, and $1 \leq l_g \leq 19$.

Habitat Separation - Four-Patch Domain



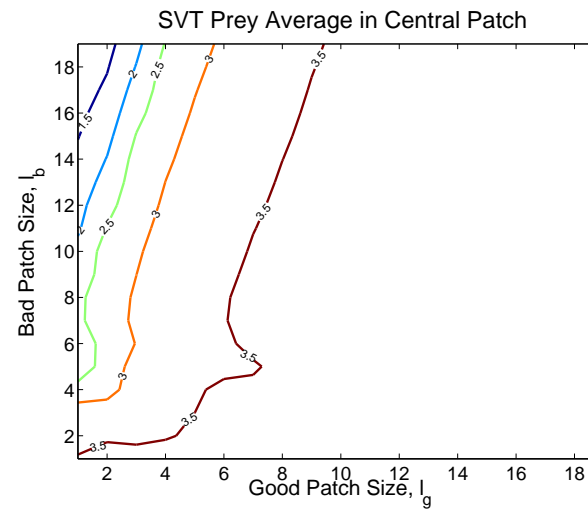
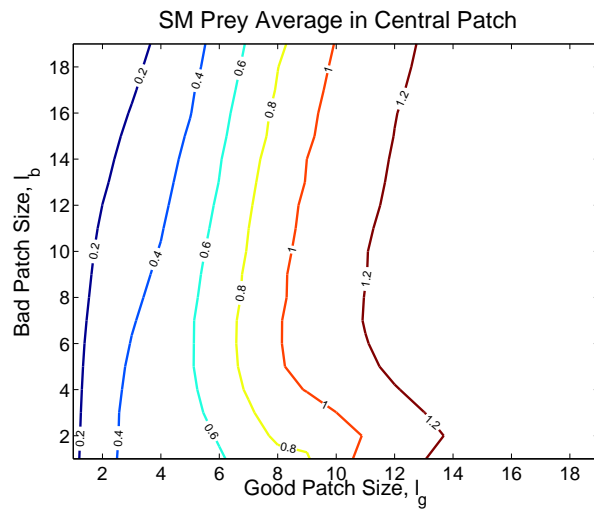
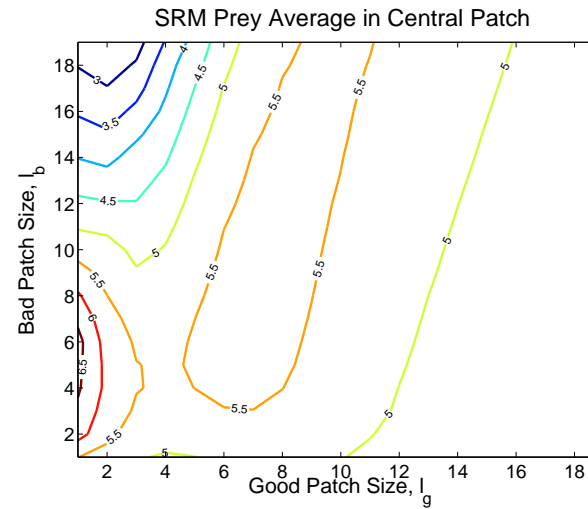
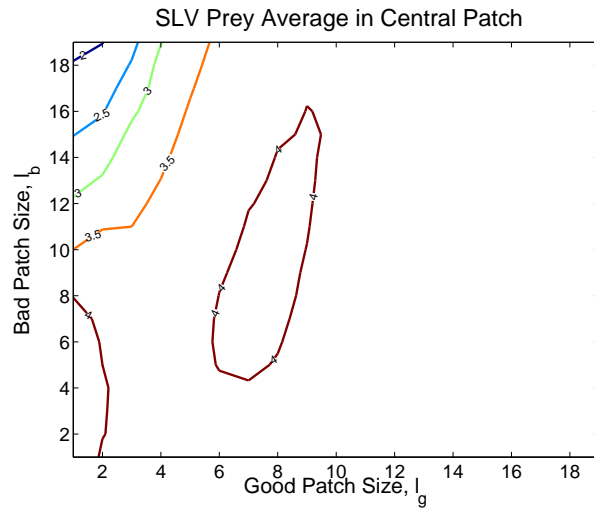
Domain: $n_g = n_b = 2$, $l_b = 12$, and $1 \leq l_g \leq 19$.

Fragmentation Space

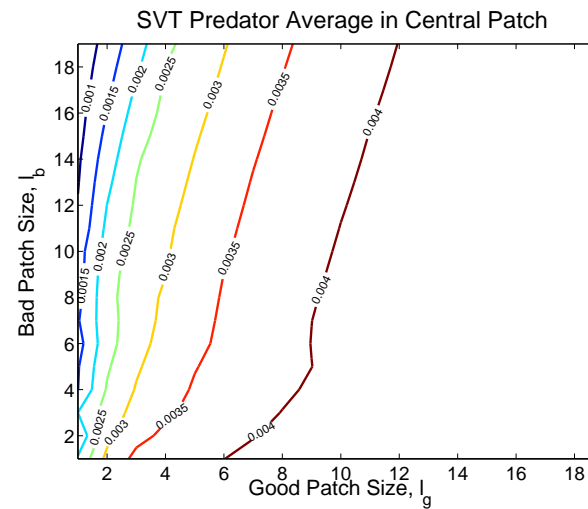
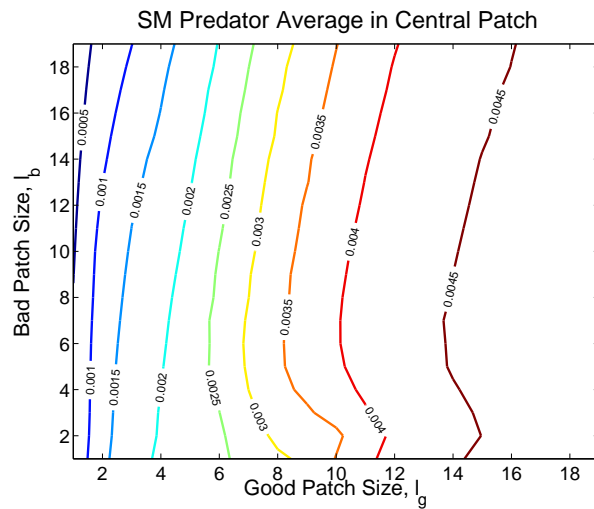
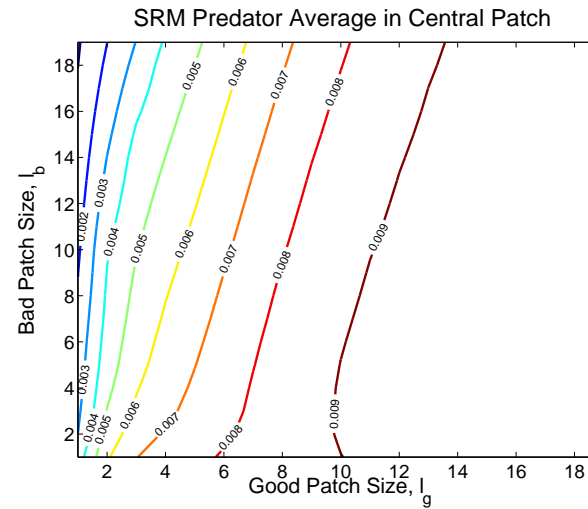
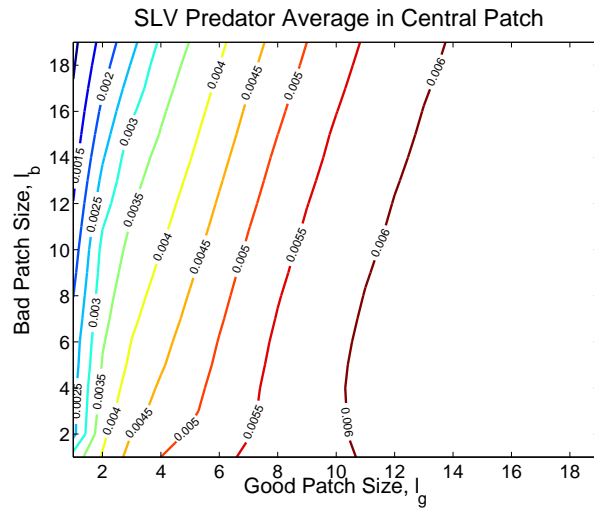


-▶ Combined Habitat Separation and Loss
- ▶ Habitat Loss
- - - -▶ Habitat Separation

Central Good Patch, Prey Average



Central Good Patch, Predator Average



Conclusions

- **General:**
 - Habitat Loss & Combined Loss - similar
 - Good patch size is more important than bad patch size
- **Ecological Implications (Combined Loss):**
 - Cycle amplitude decreases with fragmentation
 - Thresholds may be present

Model Simplification - Prey

Consider the system linearized around the trivial steady state.

$$\frac{\partial n}{\partial t} = rn + D_n \frac{\partial^2 n}{\partial x^2}$$

where

$$0 \leq x \leq L, \quad n(0, t) = n(L, t) = 0.$$

The solution is

$$n(x, t) = \sum_{m=1}^{\infty} A_m e^{[r - D_n (m\pi/L)^2]t} \sin\left(\frac{m\pi x}{L}\right),$$

with

$$\lambda_m = r - D_n \left(\frac{m\pi}{L}\right)^2.$$

Model Simplification - Prey

The leading eigenvalue is

$$\lambda_1 = r - D_n \left(\frac{\pi}{L} \right)^2$$

and so the leading order term in the solution is

$$A_1 e^{[r - D_n (\pi/L)^2]t}.$$

This quantity is the exact solution to the ordinary differential equation

$$\frac{dn}{dt} = \left(r - D_n \left(\frac{\pi}{L} \right)^2 \right) n.$$

Thus we can determine persistence in the spatial model using λ_1 .

Model Simplification - Predator

Linearizing about $(n, p) = (n^*, 0)$ where n^* =some constant.

$$\frac{\partial p}{\partial t} = \chi c n^* p - \delta p + D_p \frac{\partial^2 n}{\partial x^2},$$

where

$$0 \leq x \leq L, \quad n(0, t) = n(L, t) = 0.$$

The leading order dynamics are governed by

$$\frac{dp}{dt} = \left(\chi c n^* - \delta - D_p \left(\frac{\pi}{L} \right)^2 \right) p.$$

Spatially Implicit Growth and Death Rates

Define:

$$r_L = r - D_n \left(\frac{\pi}{L} \right)^2 ,$$

$$\delta_L = \delta + D_p \left(\frac{\pi}{L} \right)^2 ,$$

$$s_L = s - D_p \left(\frac{\pi}{L} \right)^2 .$$

Rewrite the growth and death rates using the eigenvalues above.

Spatially Implicit Models

LV

$$\frac{dn}{dt} = r_L n - cnp,$$
$$\frac{dp}{dt} = \chi cnp - \delta_L p.$$

RM

$$\frac{dn}{dt} = \left(r_L - \frac{n}{k} \right) n - \frac{cnp}{d+n},$$
$$\frac{dp}{dt} = \frac{\chi cnp}{d+n} - \delta_L p.$$

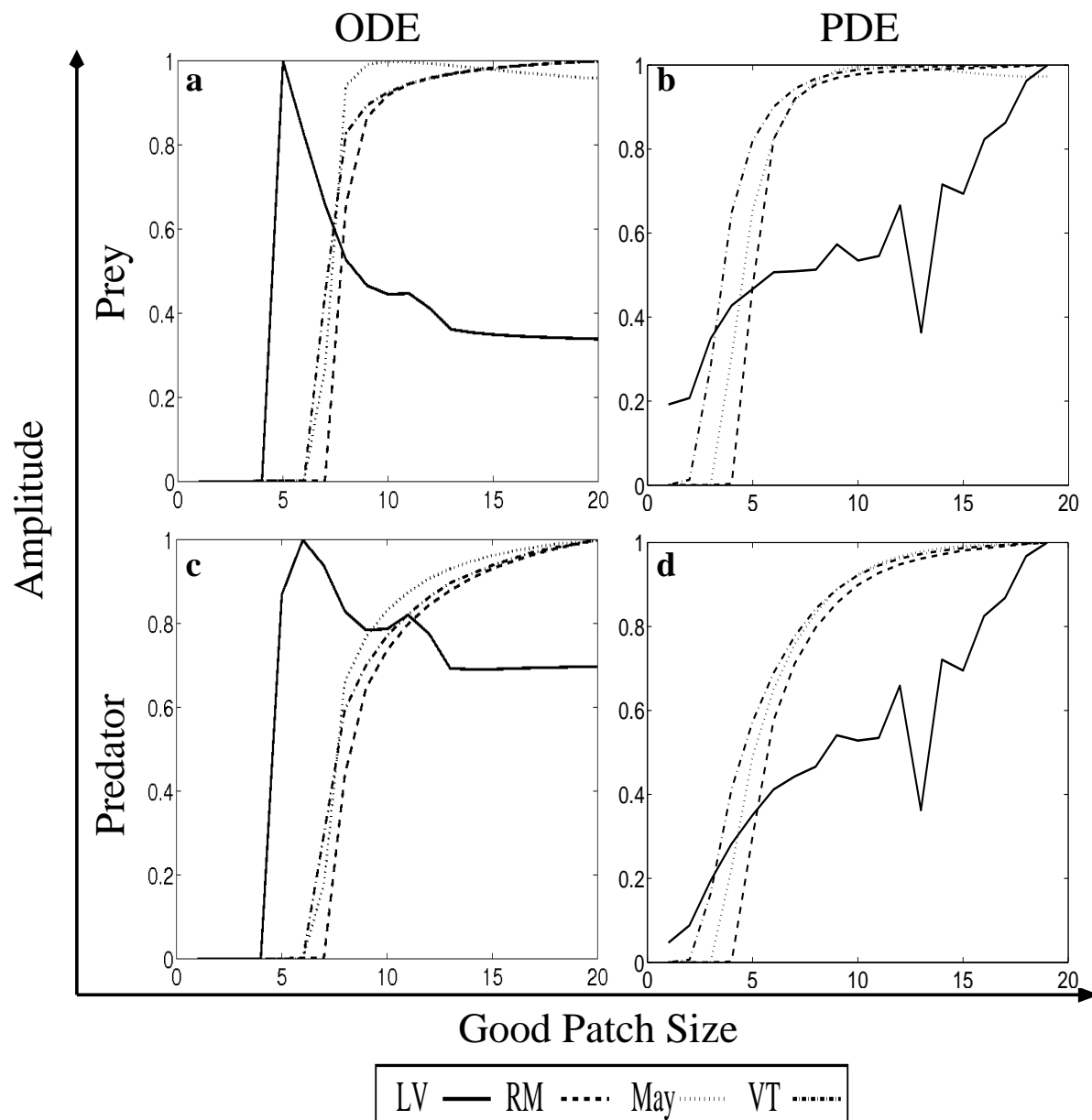
May

$$\frac{dn}{dt} = \left(r_L - \frac{n}{k} \right) n - \frac{cnp}{d+n},$$
$$\frac{dp}{dt} = p \left(s_L - \frac{qp}{n} \right).$$

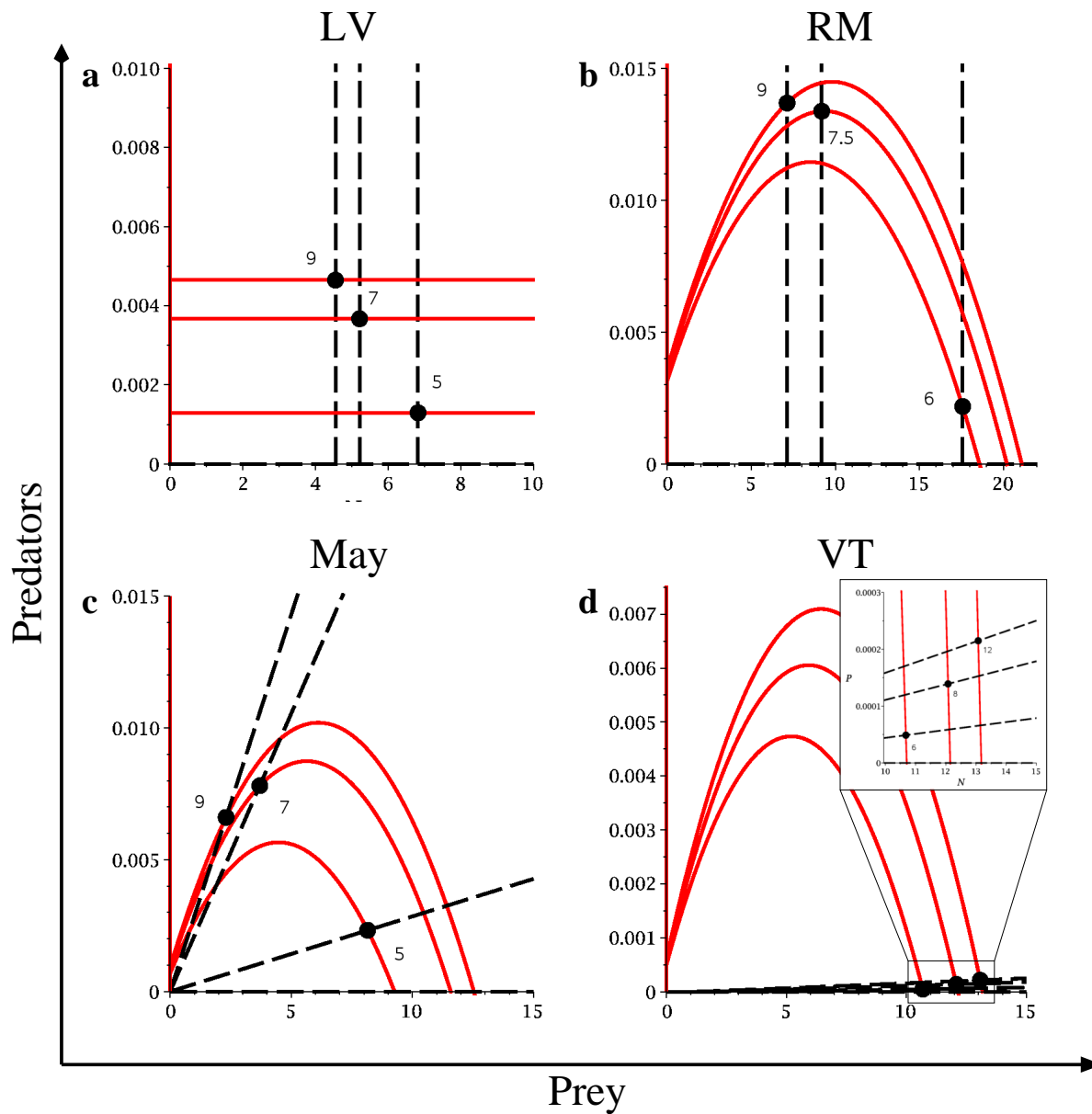
VT

$$\frac{dn}{dt} = \left(r_L - \frac{n}{k} \right) n - \frac{cnp}{d+n},$$
$$\frac{dp}{dt} = \frac{\chi cnp}{d+n} - \delta_L p - \frac{sqp^2}{n}.$$

Comparison of ODE & PDE Solutions



Nullclines



Fragmentation with Edge Behaviour



Edge Behaviour

$$D_1 \frac{\partial u_1}{\partial x} = D_2 \frac{\partial u_2}{\partial x},$$
$$u_1 = \frac{\alpha D_2}{1 - \alpha D_1} u_2,$$

where,

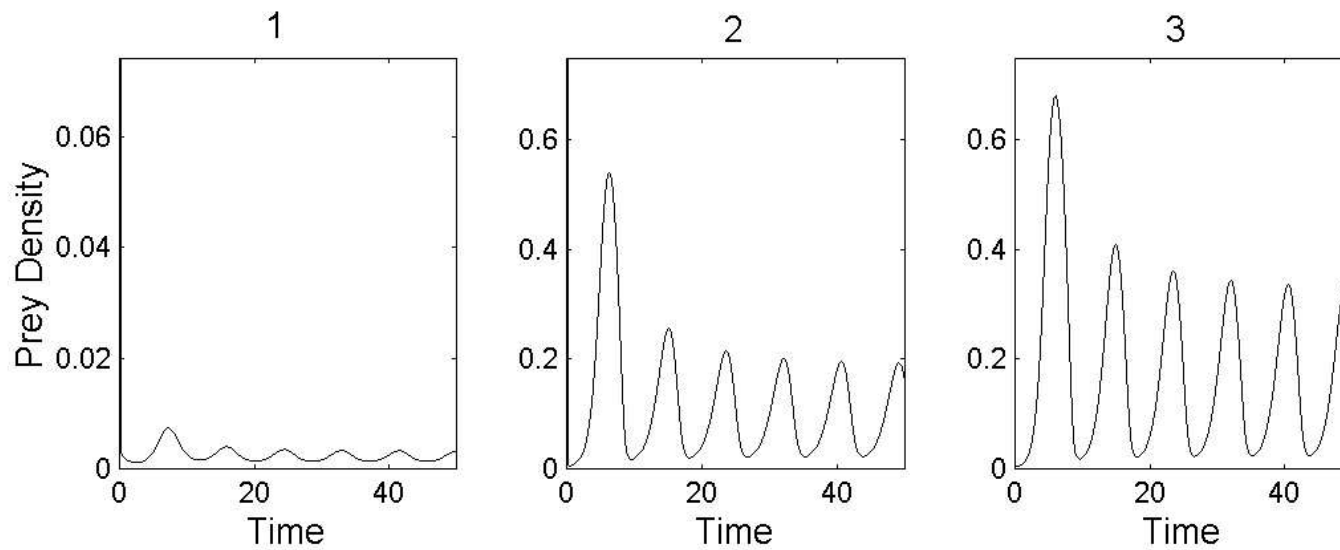
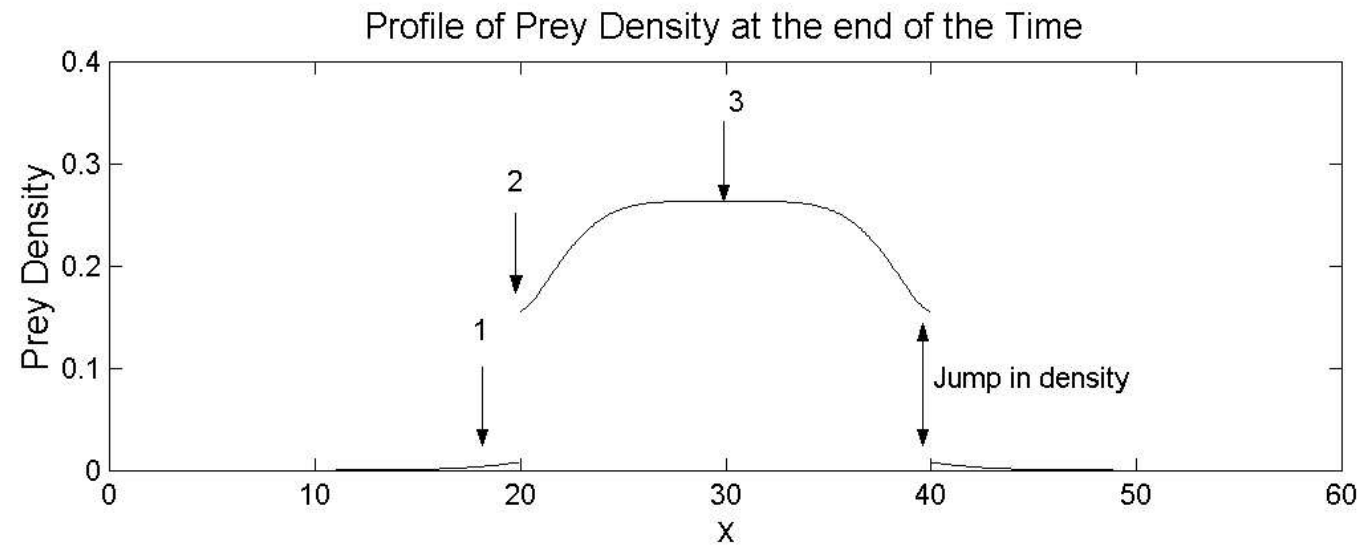
D_1, D_2 = the diffusivity coefficients in patches 1 and 2,

u_1, u_2 = the population densities at the edge of patches 1 and 2.

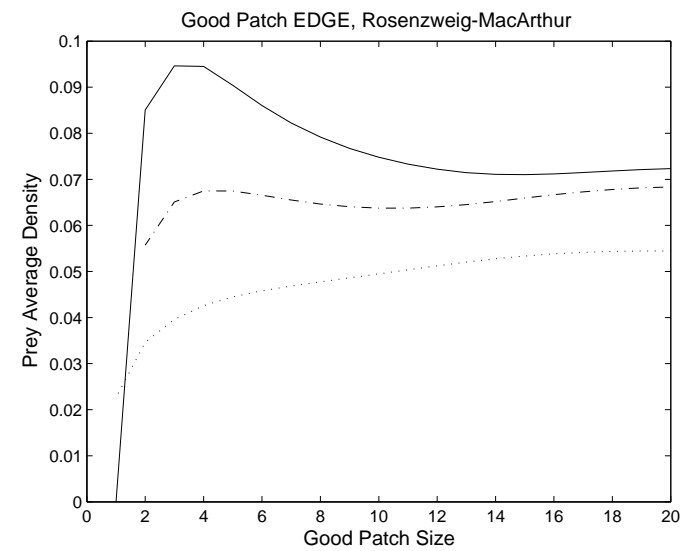
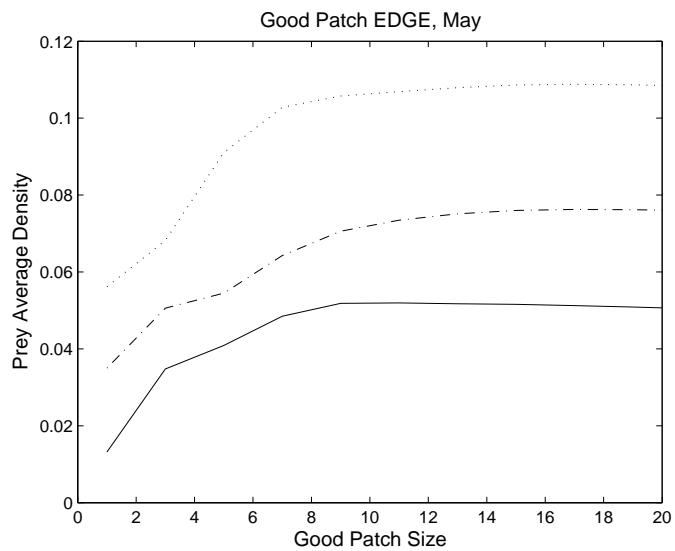
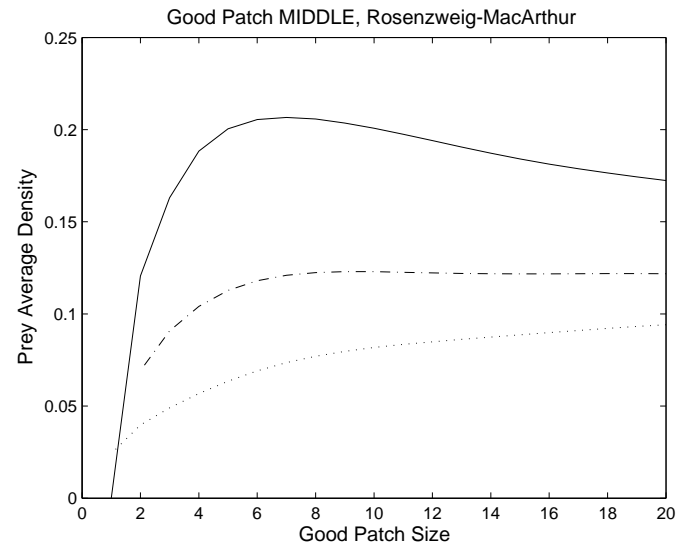
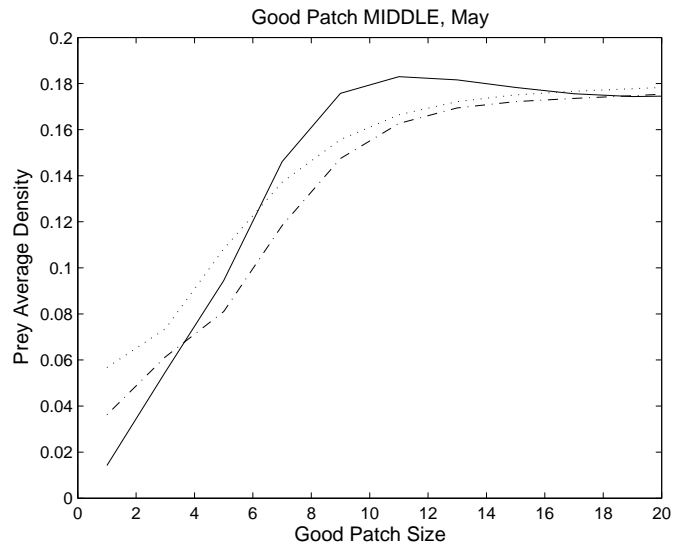
Ovaskainen & Cornell (2003) J. Applied Probability

Maciel & Lutscher (2013) Am Nat

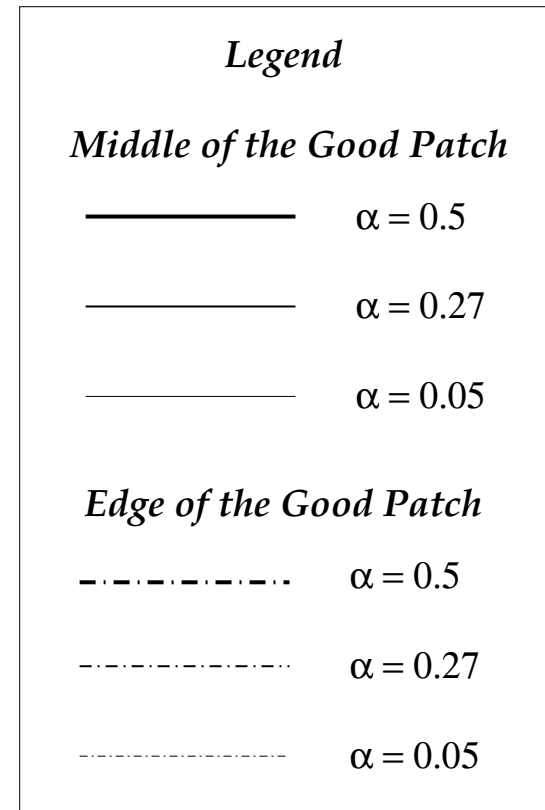
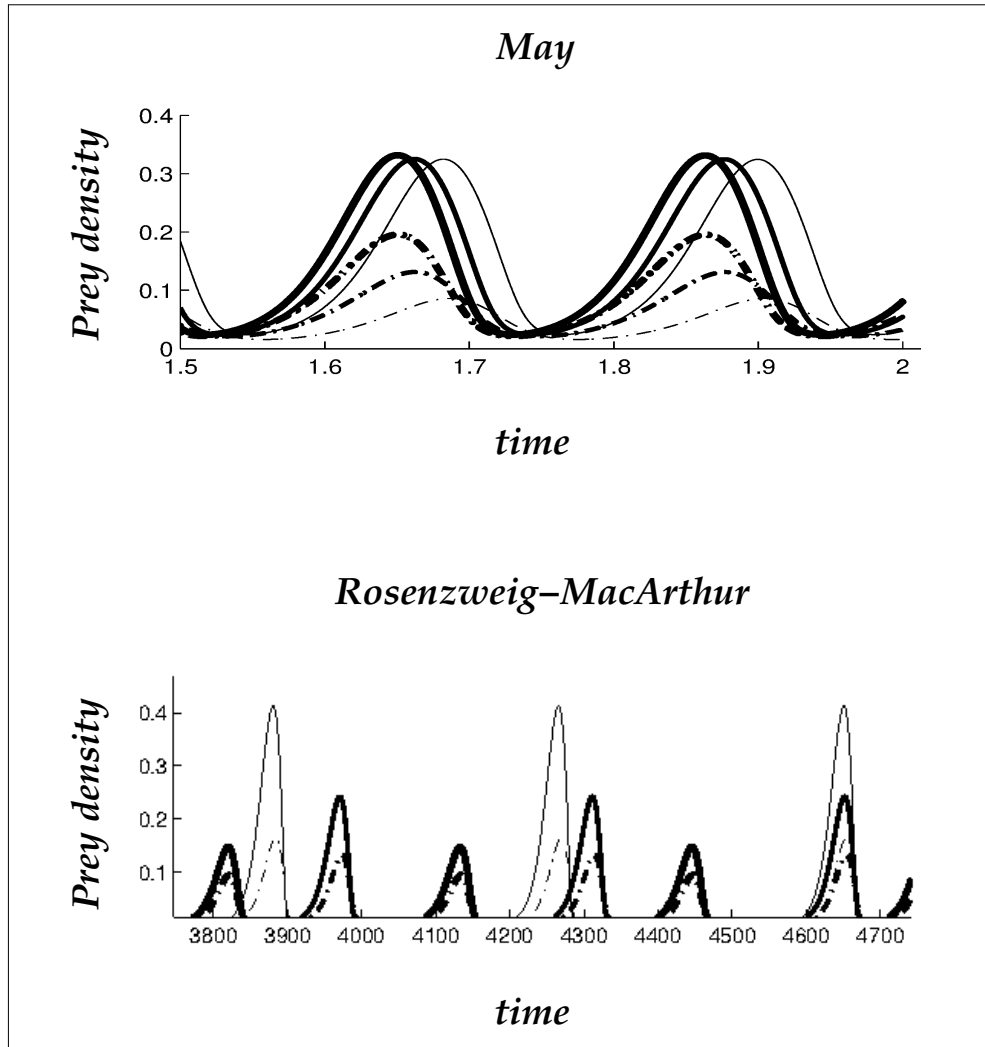
Prey Only



Effect of Good Patch Size



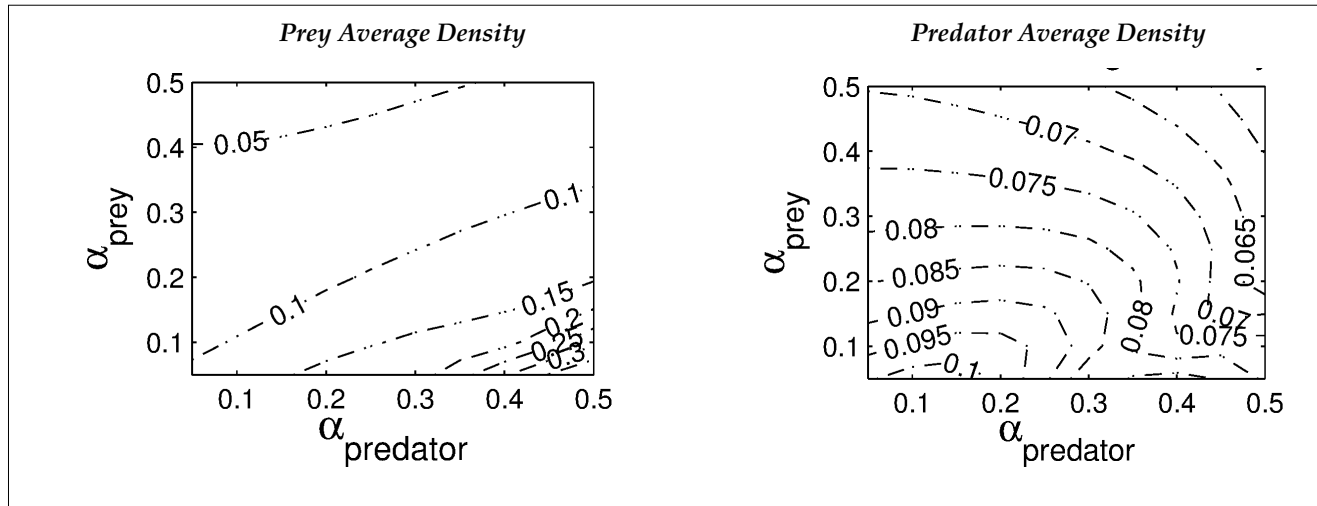
Effect of Patch Preference



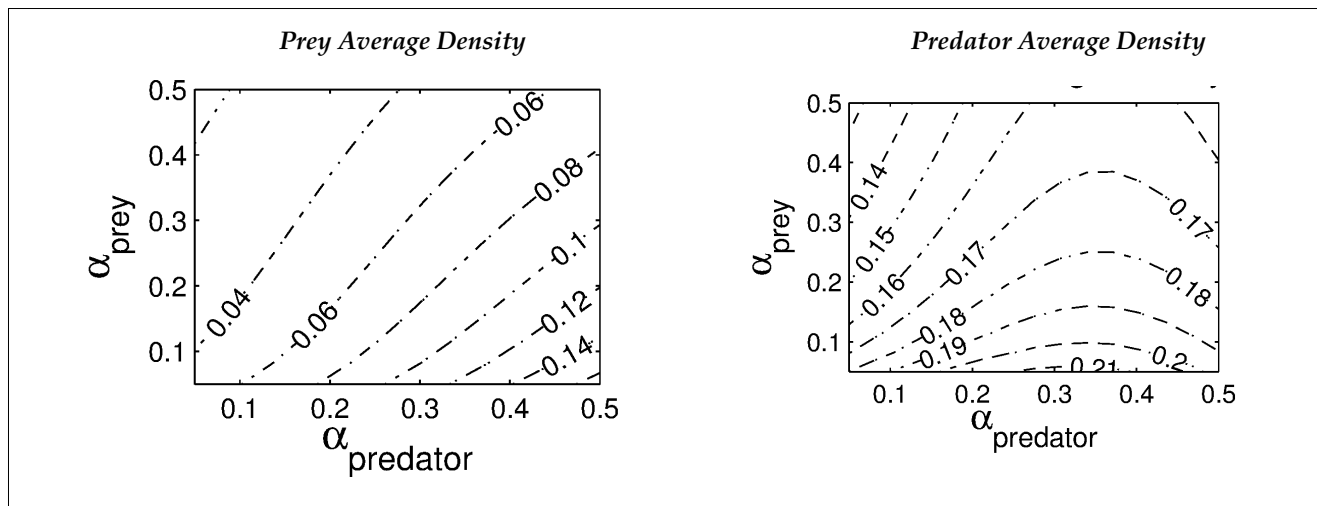
Different Patch Preference

Good Patch EDGE

May Model



Rosenzweig-MacArthur Model



Snowshoe hare

Oh my gosh, I've got to run -
Lynx is here to spoil the fun.
My feet are built to tread the snow,
But so are hers, you ought to know.
Oh no, she's gaining - a spurt of speed -
Am I to be her bunny feed?
Zig, zag, dash - I'm past her,
Today *my* furry feet are faster!
I never ever want to lose
My lucky little running shoes.

from Lucky Hares and Itchy Bears, (1996) by Susan
Ewing, Alaska Northwest Books, Portland, OR.



